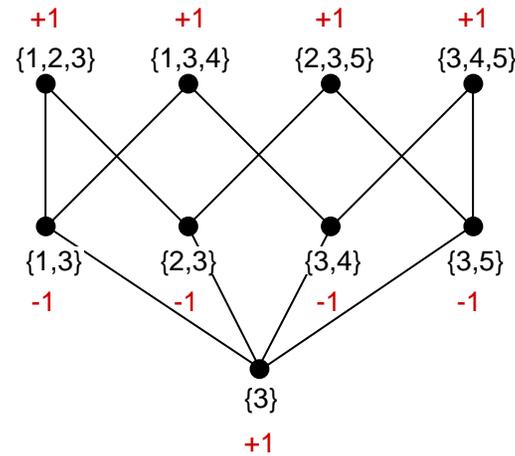


# Belief Propagation on Partially Ordered Sets

Robert J. McEliece

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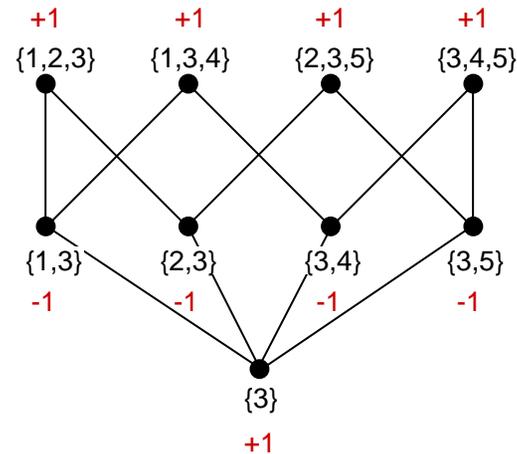


International Symposium on  
Mathematical Theory of Networks and Systems  
University of Notre Dame  
August 13, 2002

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\* *With much help from Muhammed Yildirim, Jonathan Harel, Jeremy Thorpe, and Ravi Palanki.*

## A Big Tip of the Hat to:

Jonathan Yedidia, William Freeman,  
and Yair Weiss, the authors of

*“Generalized Belief Propagation  
and Free Energy Minimization,”*

which inspired this paper.

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- Coffee Break

## A General Computational Problem

- Variables  $\{x_1, \dots, x_n\}$ ,  $x_i \in A = \{0, 1, \dots, q - 1\}$ .
- $\mathcal{R} = \{R_1, \dots, R_M\}$ , a collection of subsets of  $\{1, 2, \dots, n\}$ .
- A set of nonnegative “local potentials”  $\{\alpha_R(\mathbf{x}_R) : R \in \mathcal{R}\}$ .

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- A set of nonnegative “local potentials”  $\{\alpha_R(\mathbf{x}_R) : R \in \mathcal{R}\}$ .
- Define the global (Boltzmann) probability density function;

$$B(\mathbf{x}) = \frac{1}{Z} \prod_{R \in \mathcal{R}} \alpha_R(\mathbf{x}_R),$$

where

$$Z = \sum_{\mathbf{x} \in A^n} \prod_{R \in \mathcal{R}} \alpha_R(\mathbf{x}_R) \quad (\text{Partition function})$$

( $F = -\ln Z = \text{Helmholtz free energy}$ ).

## A General Computational Problem, Continued

**Problem:** Compute, *exactly or approximately*, the Helmholtz free energy  $F$  and some or all of the *local marginal densities* of the Boltzmann density:

$$\begin{aligned} B_R(\mathbf{x}_R) &= \sum_{\mathbf{x}_{R^c} \in A^{R^c}} B(\mathbf{x}) \\ &= \frac{1}{Z} \sum_{\mathbf{x}_{R^c} \in A^{R^c}} \prod_{S \in \mathcal{R}} \alpha_S(\mathbf{x}_S), \end{aligned}$$

for  $R \in \mathcal{R}$ .

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(But we won't discuss these applications)

## A Simple Example.

Alphabet:  $A = \{0, 1\}$ .

Local domains:  $\mathcal{R} = \{\{1, 2, 3\}, \{1, 3, 4\}, \{2, 3, 5\}, \{3, 4, 5\}\}$ .

Local potentials:

$$\alpha_i(x, y, z) = \begin{cases} 1/2 & \text{if } x = y = z \\ 0 & \text{otherwise} \end{cases} \quad i = 1, 2, 3, 4.$$

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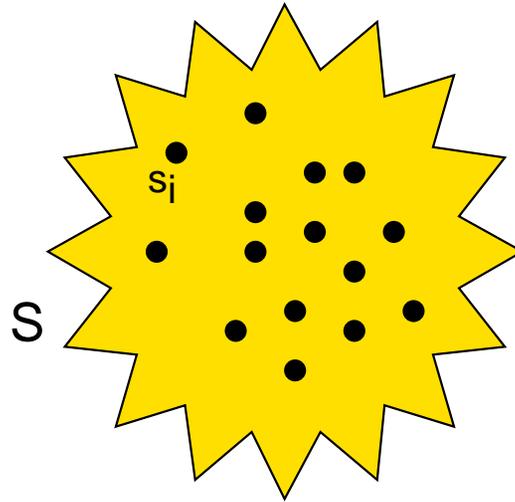
Answers:  $Z = 1/8$

$$F = \ln 8.$$

$$B(x_1, x_2, x_3, x_4, x_5) = \begin{cases} 1/2 & \text{if } x_1 = x_2 = \cdots = x_5 \\ 0 & \text{otherwise.} \end{cases}$$

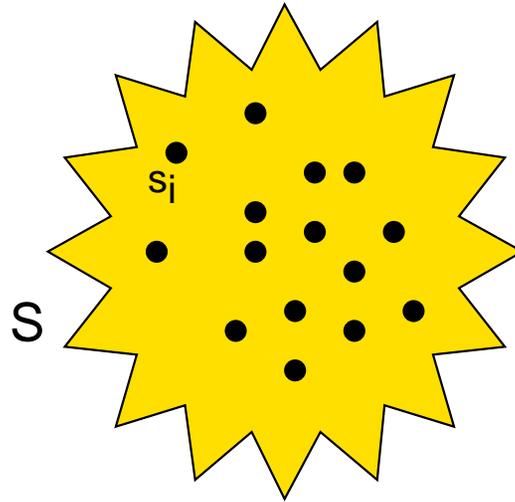
$$B_i(x, y, z) = \begin{cases} 1/2 & \text{if } x = y = z \\ 0 & \text{otherwise} \end{cases}$$

# A Statistical Physics Approach



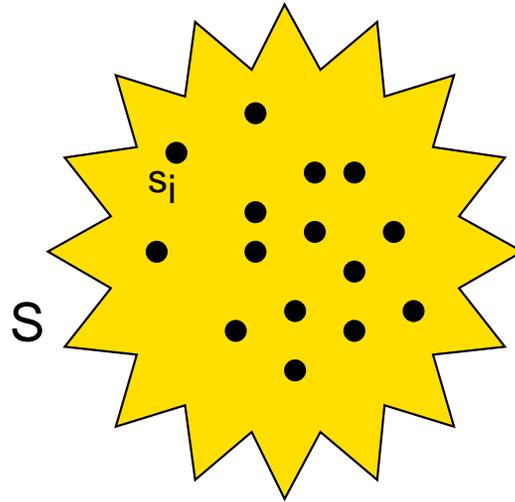
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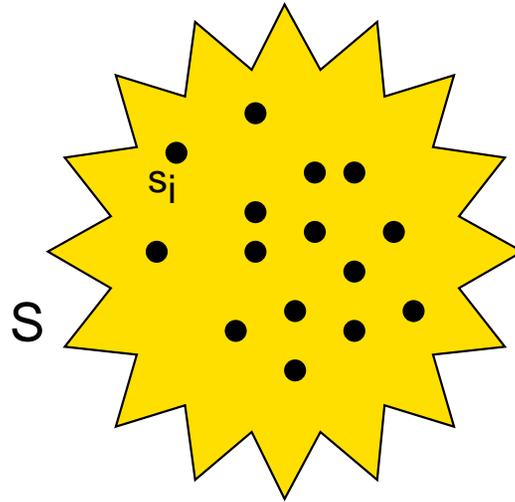
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- “Spin” of  $s_i = x_i \in A = \{0, 1, \dots, q - 1\}$ .
- System “configuration”  $\mathbf{x} = (x_1, x_2, \dots, x_n)$ .
- $E(x_1, \dots, x_n) =$  energy of configuration  $\mathbf{x}$ . (Hamiltonian)  
 $= - \sum_{R \in \mathcal{R}} \ln \alpha_R(\mathbf{x}_R)$ .

## A Statistical Physics Approach

- $b(\boldsymbol{x})$  = “Trial” probability of configuration  $\boldsymbol{x}$ .

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- Entropy:  $H = - \sum_{\mathbf{x} \in A^n} b(\mathbf{x}) \ln b(\mathbf{x})$ .
- Variational free energy:

$$\tilde{F}(b) = U - H.$$

## A Famous Theorem from Statistical Mechanics

**Theorem.**

$$\tilde{F}(b) \geq F,$$

*with equality if and only if*

$$b(\mathbf{x}) = B(\mathbf{x}) = \frac{1}{Z} e^{-E(\mathbf{x})},$$

*the Boltzmann-Gibbs, or equilibrium, density.*

## Proof of the Famous Theorem

A simple calculation shows that

$$\tilde{F}(b) = D(b \parallel B) + F.$$

Hence

$$\tilde{F}(b) \geq F,$$

with equals iff  $b = B$ .

## An Important Corollary

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$$F = \min_{b(\mathbf{x})} \tilde{F}(b)$$

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- Suggests a possible method for computing  $F$  (and  $B(\mathbf{x})$ ), but as it stands, it's too complex, and anyway it doesn't yield the marginals  $B_R(\mathbf{x}) \dots$

# A Solution Using Belief Propagation on a Partially Ordered Set

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(But What is a Partially Ordered Set?)

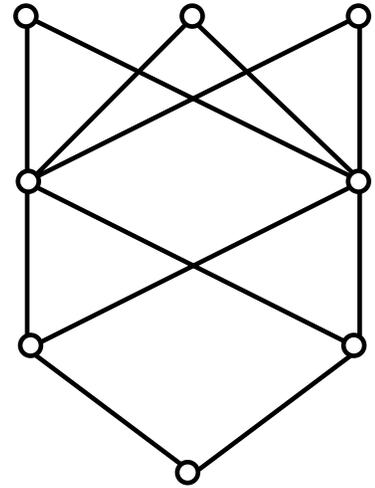
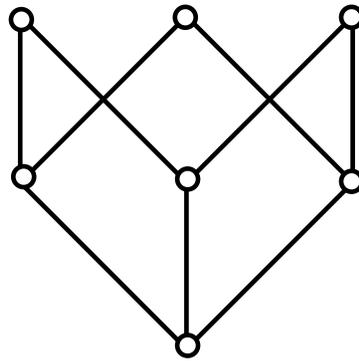
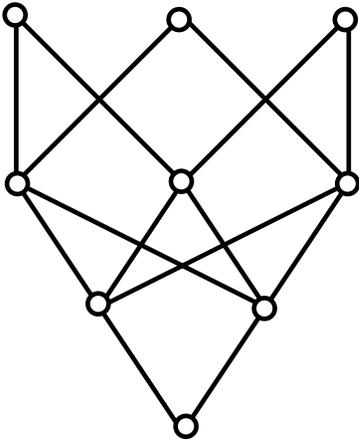
# A Solution Using Belief Propagation on a Partially Ordered Set

(But What is a Partially Ordered Set?)

A finite *partially ordered set* is a finite set  $P$  together with a binary relation, denoted  $\leq$ , which satisfies the following three axioms:

1. For all  $\rho \in P$ ,  $\rho \leq \rho$ . (*reflexivity*)
2. If  $\rho \leq \sigma$  and  $\sigma \leq \rho$ , then  $\rho = \sigma$ . (*antisymmetry*)
3. If  $\rho \leq \sigma$  and  $\sigma \leq \tau$ , then  $\rho \leq \tau$ . (*transitivity*)

# Hasse Diagrams for Three Posets



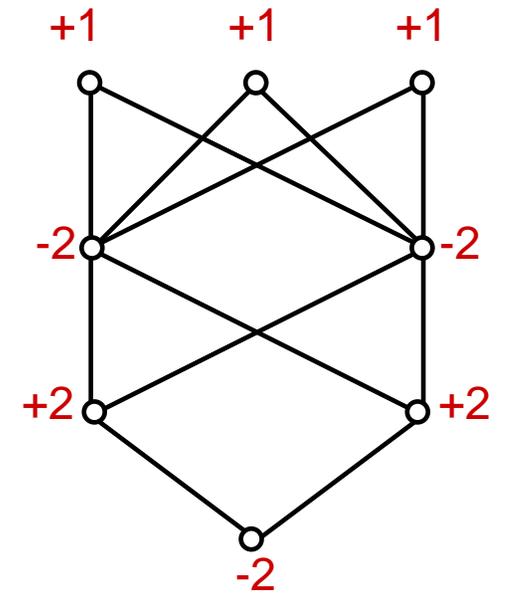
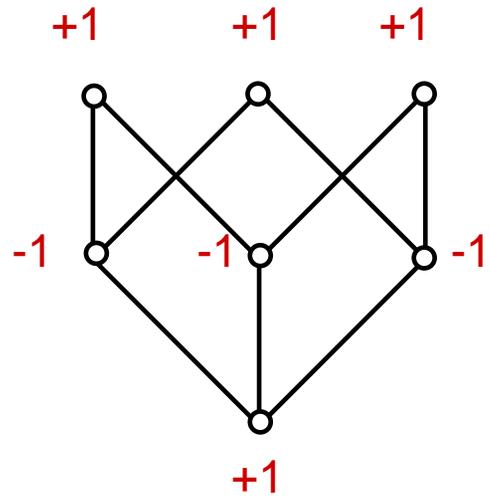
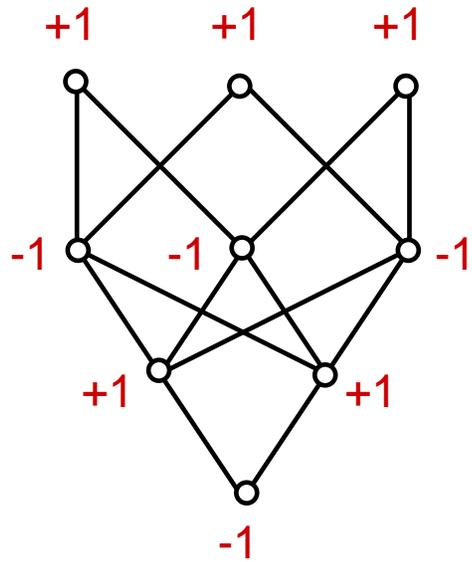
## Overcounting Numbers for Posets

We assign an *overcounting number*  $\phi(\rho)$  to each  $\rho \in P$ , such that

$$(1) \quad \sum_{\rho: \rho \geq \sigma} \phi(\rho) = 1, \text{ for all } \sigma \in P.$$

The overcounting numbers  $\phi(\rho)$  are integers and are determined uniquely by (1).

# Some Overcounting Numbers



## How to Distribute the Local Potentials in a Given Poset $P$ .

Step 1: Assign each variable  $x_i$  to one or more elements of  $P$ . If  $P_i = \{\rho \in P : x_i \text{ is assigned to } \rho\}$ , then we require:

- $P_i$  is connected;
- $P_i$  is closed under  $\geq$ , i.e., if  $x_i$  is assigned to  $\rho$  it is also assigned to all of  $\rho$ 's “superiors;”
- $\phi(P_i) = 1$ , i.e., the net number of appearances of  $x_i$  is 1.

We denote by  $D(\rho)$  (the local domain at  $\rho$ ) the set of variables which are assigned to  $\rho$ .

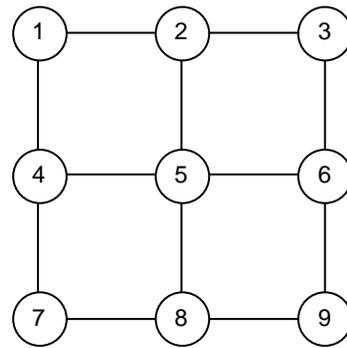
## How to Distribute the Local Potentials in a Given Poset $P$ .

Step 2: Assign each local potential  $\alpha_R(\mathbf{x}_R)$  to one or more elements of  $P$ . If  $P_R = \{\rho \in P : \alpha_R(\mathbf{x}_R) \text{ is assigned to } \rho\}$ , then we require:

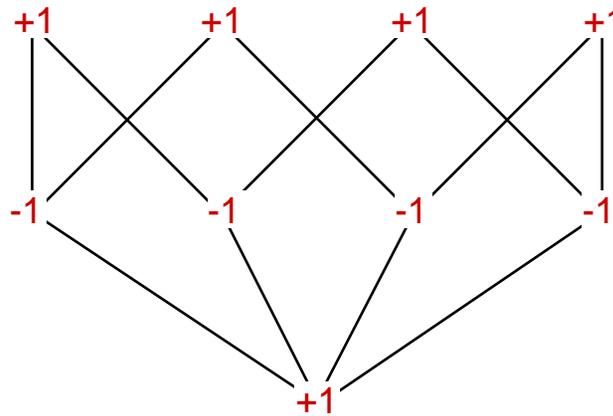
- $R \subseteq D(\rho)$  for all  $\rho \in P_R$ , i.e., the local domain at  $\rho$  supports  $\alpha_R(\mathbf{x}_R)$ ;
- $P_R$  is connected;
- $P_R$  is closed under  $\geq$ , i.e., if  $\alpha_R$  is known to  $\rho$  it is also known to all of  $\rho$ 's superiors;
- $\phi(P_R) = 1$ , i.e., the net number of appearances of  $\alpha_R(\mathbf{x}_R)$  is 1.

# Example: “Generalized Belief Propagation” (YF&W)

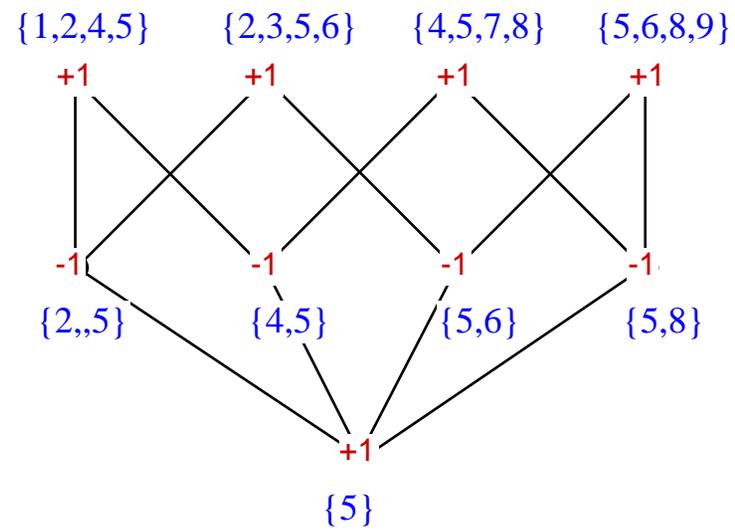
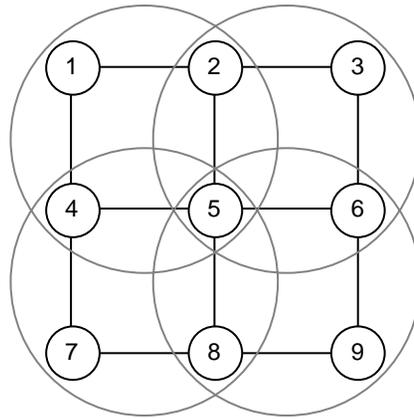
- $\mathcal{R} = \{\{1, 2\}, \{2, 3\}, \dots, \{8, 9\}\}$ :



- Here is the poset:

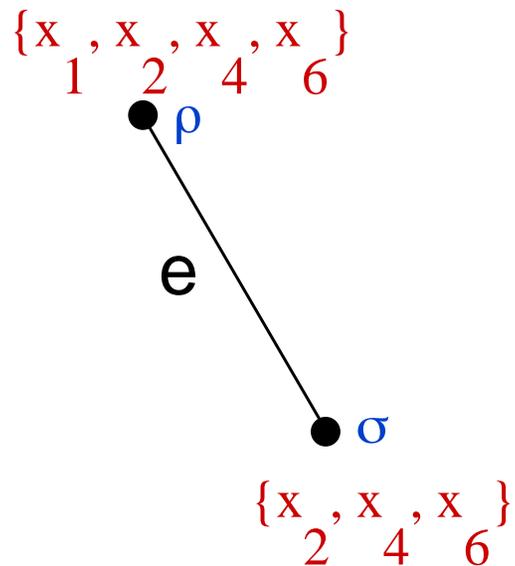


# The Trick is to Cluster the Variables



## The PBP Algorithm: The Messages.

- Throughout the algorithm, each edge  $e = (\rho, \sigma)$  of the Hasse diagram carries a “message”  $m_e$ .
- The message  $m_e$  on the edge  $e$  is a function on the domain of  $\sigma$ :  $m_e = m_e(\mathbf{x}_\sigma)$ .
- **Example:**



$(x_2, x_4, x_6)$	$m_e(x_2, x_4, x_6)$
$(0, 0, 0)$	1
$(0, 0, 1)$	0
$\vdots$	$\vdots$
$(1, 1, 1)$	0

## The PBP Algorithm: Calculating Beliefs.

- For a given set of messages  $\{m_e : e \in E\}$ , we define the *belief at  $\rho$*  as the following probability density on the domain at  $\rho$ :

$$b_\rho(\mathbf{x}_\rho) \propto \alpha_\rho(\mathbf{x}_\rho) \prod_{e \in E(\rho)} m_e(\mathbf{x}_{\text{fin } e}),$$

where the normalization is such that  $\sum_{\mathbf{x}_\rho} b_\rho(\mathbf{x}_\rho) = 1$ .

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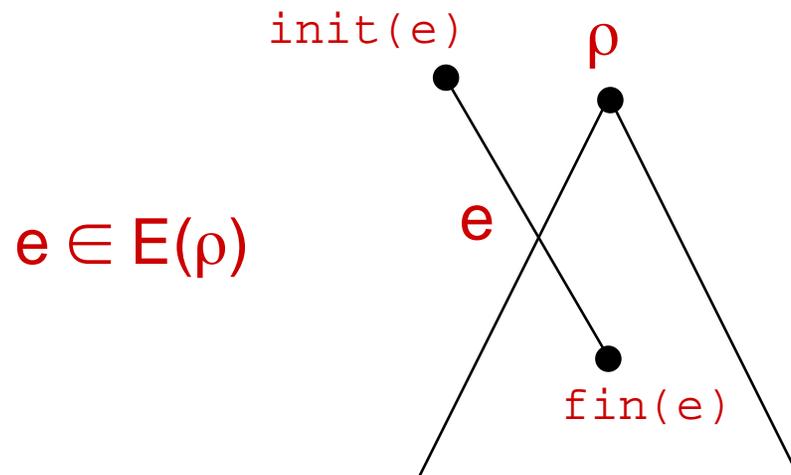
where the normalization is such that  $\sum_{\mathbf{x}_\rho} b_\rho(\mathbf{x}_\rho) = 1$ .

- Here  $\alpha_\rho(\mathbf{x}_\rho)$  is the local potential at  $\rho$ , and  $E(\rho)$  represents the set of messages which are “fused” at  $\rho$ .

## The Messages that are “Fused” at $\rho$

$$b_\rho(\mathbf{x}_\rho) \propto \alpha_\rho(\mathbf{x}_\rho) \prod_{e \in E(\rho)} m_e(\mathbf{x}_{\text{fin } e}),$$

- The messages in  $E(\rho)$  are those that originate outside  $\rho$ 's “field of view” but terminate inside it.



## The PBP Algorithm: Updating the Messages.

- An edge  $e = (\rho, \sigma)$  is said to be *consistent* with respect to a given set  $\{m_e : E \in E\}$  of messages if

$$\sum_{\mathbf{x}_\rho \setminus \mathbf{x}_\sigma} b_\rho(\mathbf{x}_\rho) = b_\sigma(\mathbf{x}_\sigma) \quad \text{for all } \mathbf{x}_\sigma \in A^{D(\sigma)}.$$

In words, this says that the belief at  $\rho$  in  $\mathbf{x}_\sigma$ , obtained by marginalization, agrees with the belief at  $\sigma$  in  $\mathbf{x}_\sigma$ .

# Example of Edge Consistency

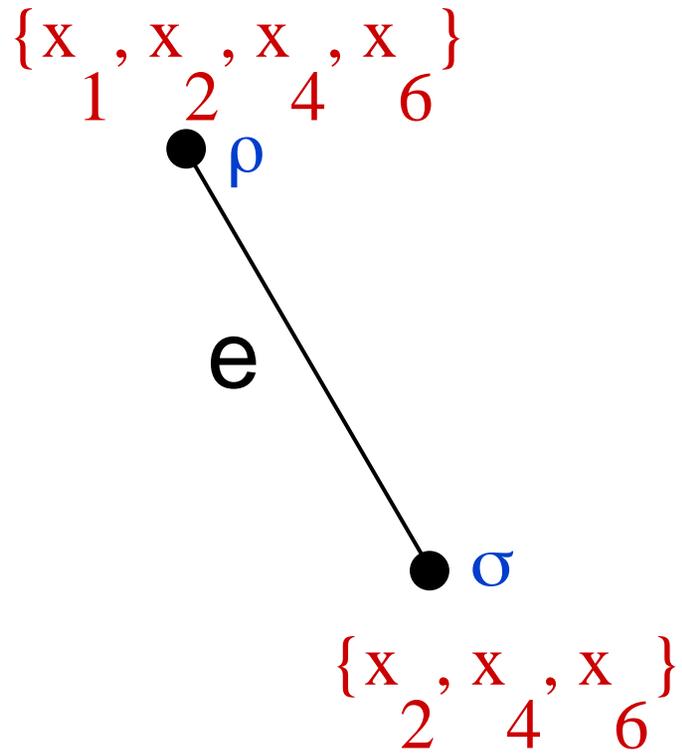
$\{x_1, x_2, x_4, x_6\}$

$\rho$

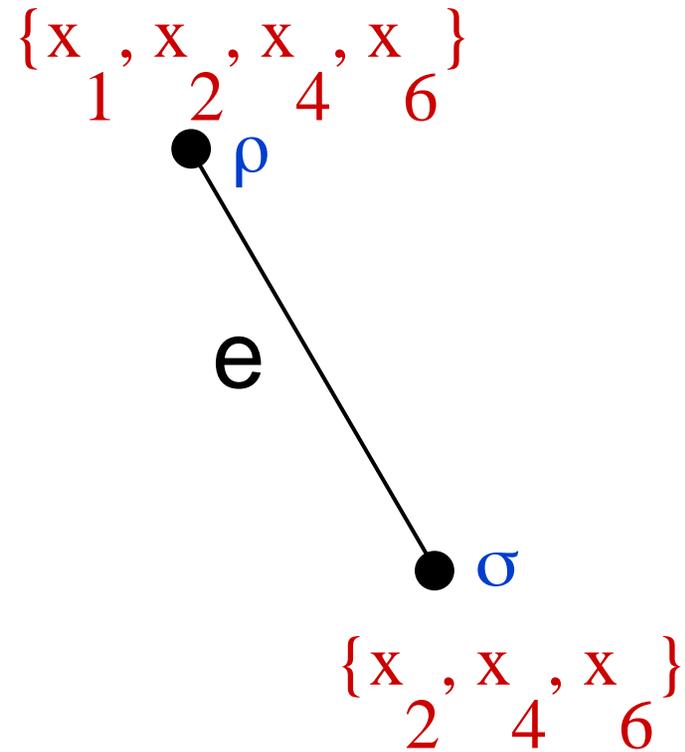
$e$

$\sigma$

$\{x_2, x_4, x_6\}$



## Example of Edge Consistency



- $e = (\rho, \sigma)$  is consistent if

$$\sum_{x_1 \in A} b_\rho(x_1, x_2, x_4, x_6) = b_\sigma(x_2, x_4, x_6)$$

## The PBP Algorithm: The Update Rule

- When the message  $m_e$  is updated, it is adjusted so that the edge  $e$  becomes *consistent*. Explicitly,

$$m_e(\mathbf{x}_\sigma) \propto \frac{\sum_{\mathbf{x}_\rho \setminus \mathbf{x}_\sigma} \left( \alpha_{\rho \setminus \sigma}(\mathbf{x}_\rho) \prod_{g \in E(\rho) \setminus E(\sigma)} m_g(\mathbf{x}_{\text{fin}(g)}) \right)}{\prod_{f \in E(\sigma) \setminus \{E(\rho) \cup e\}} m_f(\mathbf{x}_{\text{fin}(f)})}.$$

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- The PBP algorithm proceeds by updating messages according to this rule. The hope is that the messages will converge to a fixed point whose associated beliefs are good approximations to the desired marginals, i.e.,

$$b_\rho(\mathbf{x}_\rho) \approx B_\rho(\mathbf{x}_\rho),$$

where  $B(\mathbf{x})$  is the global or “Boltzmann” density.

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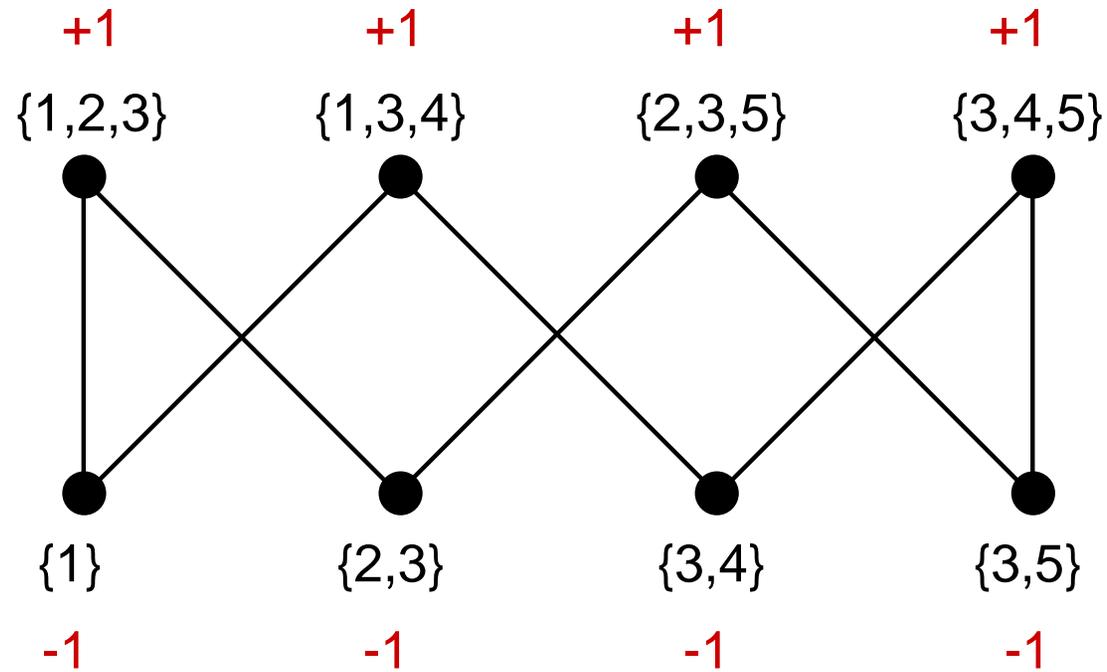
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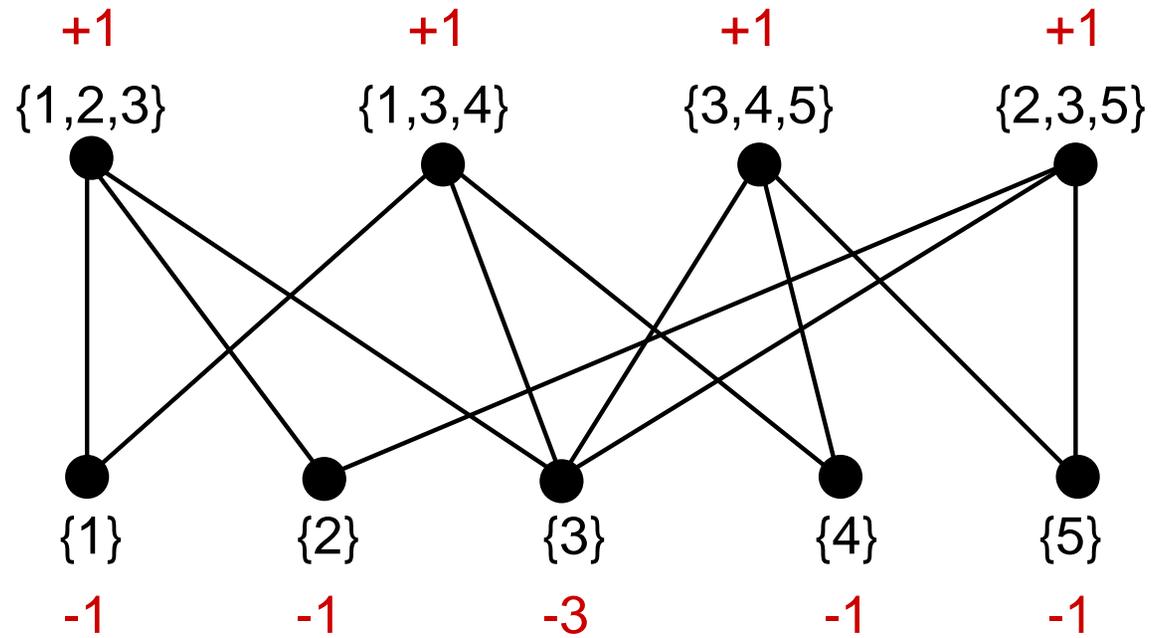
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- There are many posets that support this choice of domains; we will investigate only three.

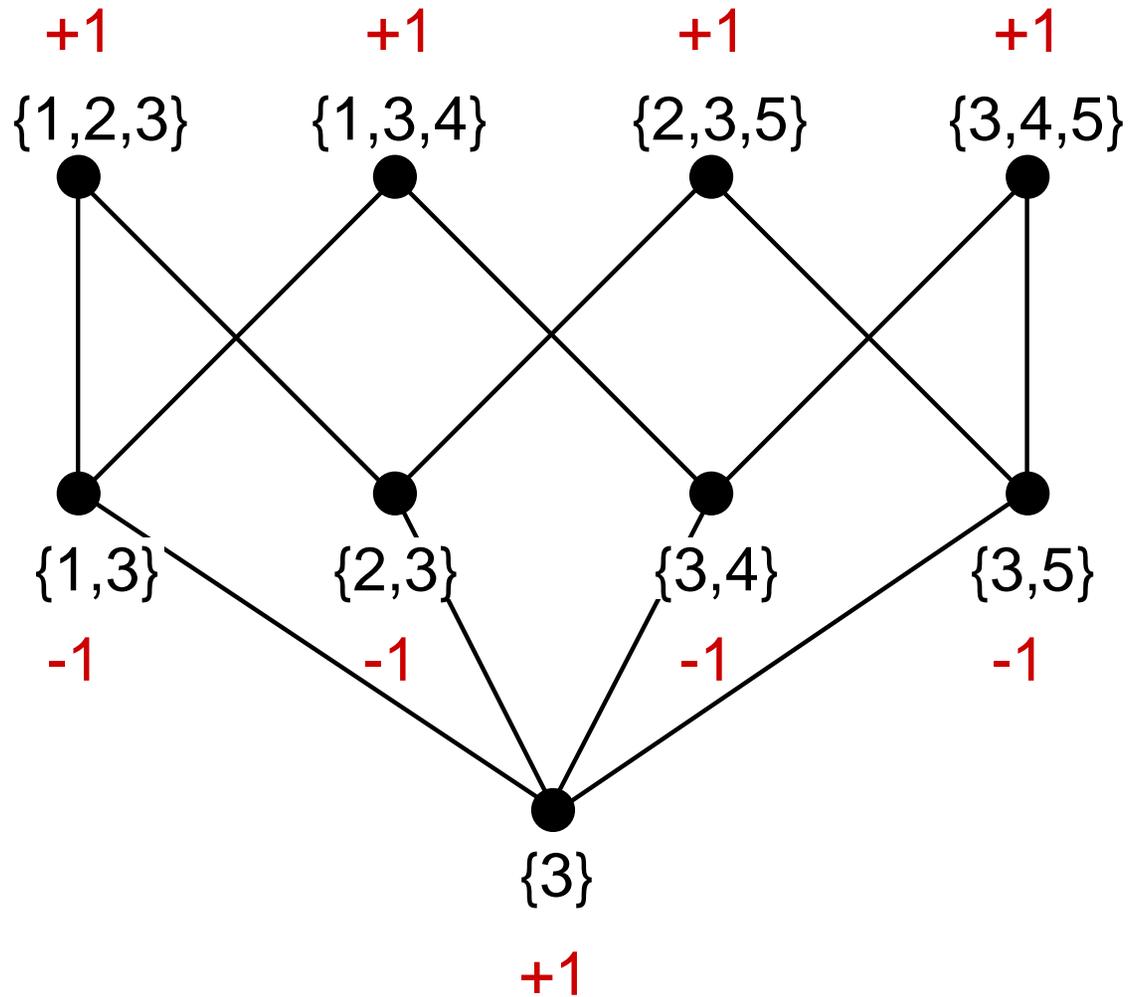
# Poset Number One (Junction Graph Construction)



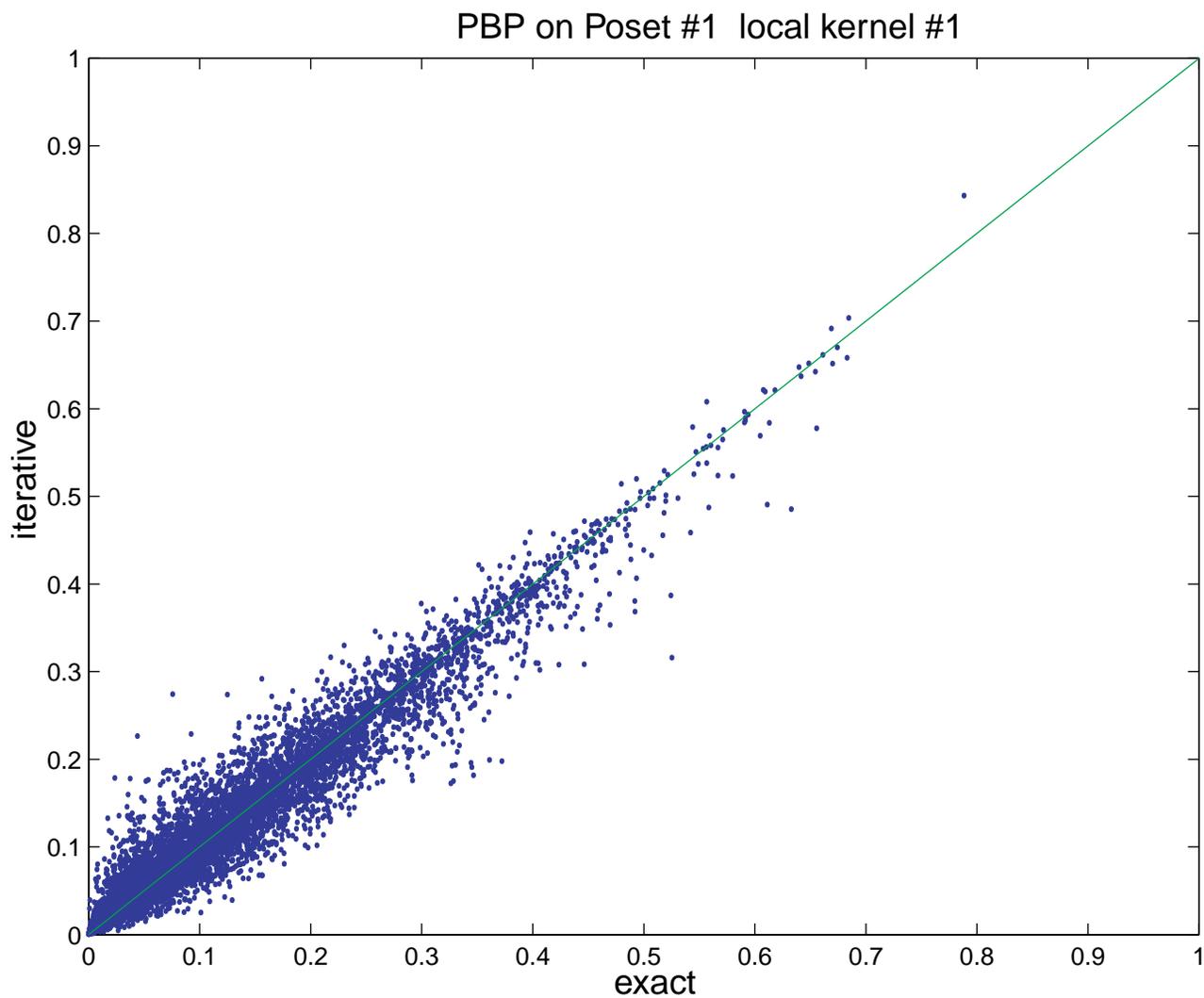
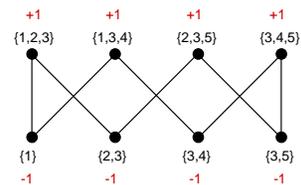
## Poset Number Two (Factor Graph Construction)



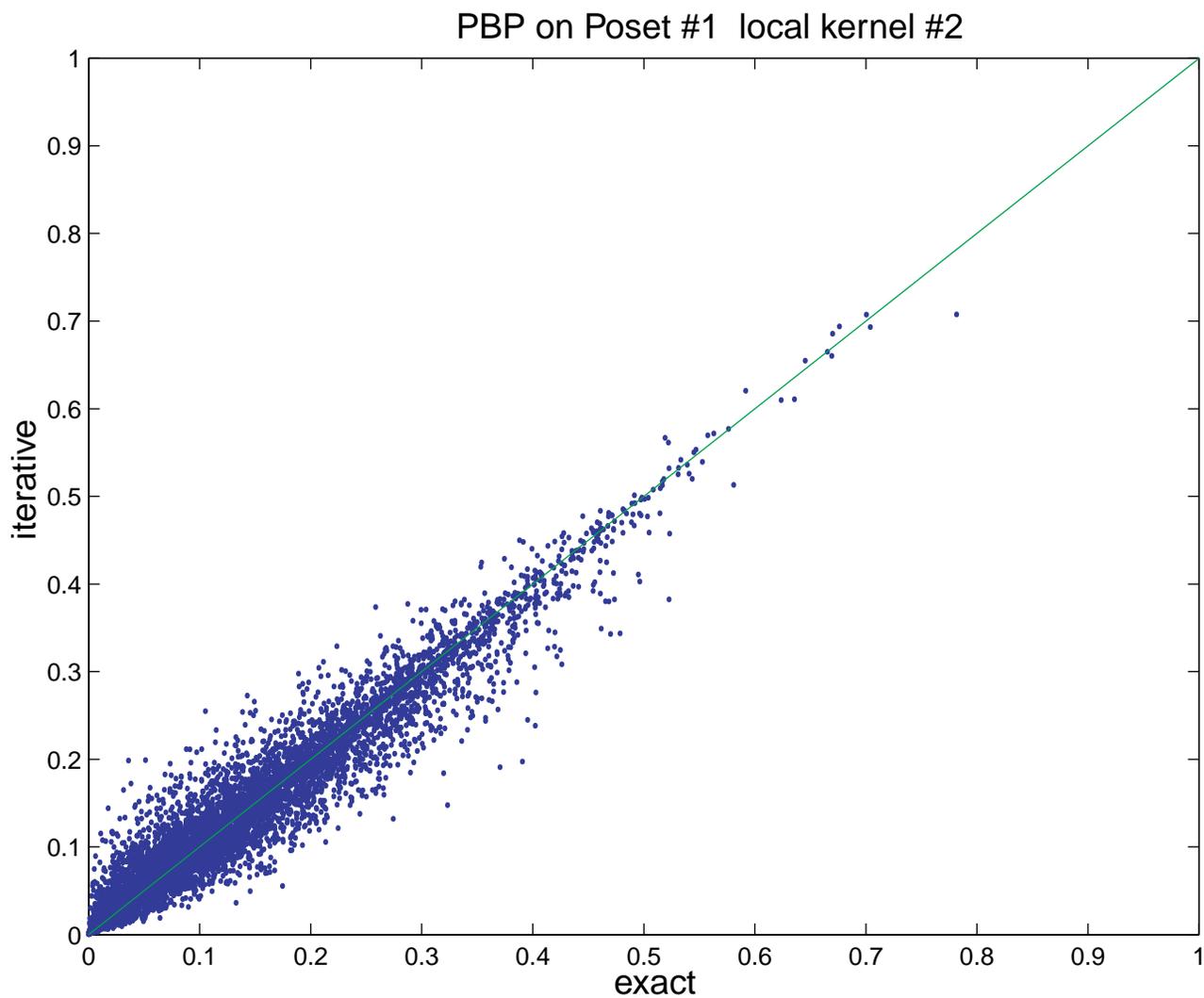
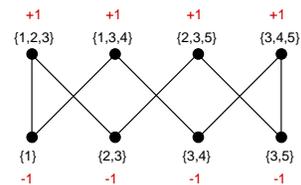
# Poset Number Three (Cluster Variational Method)



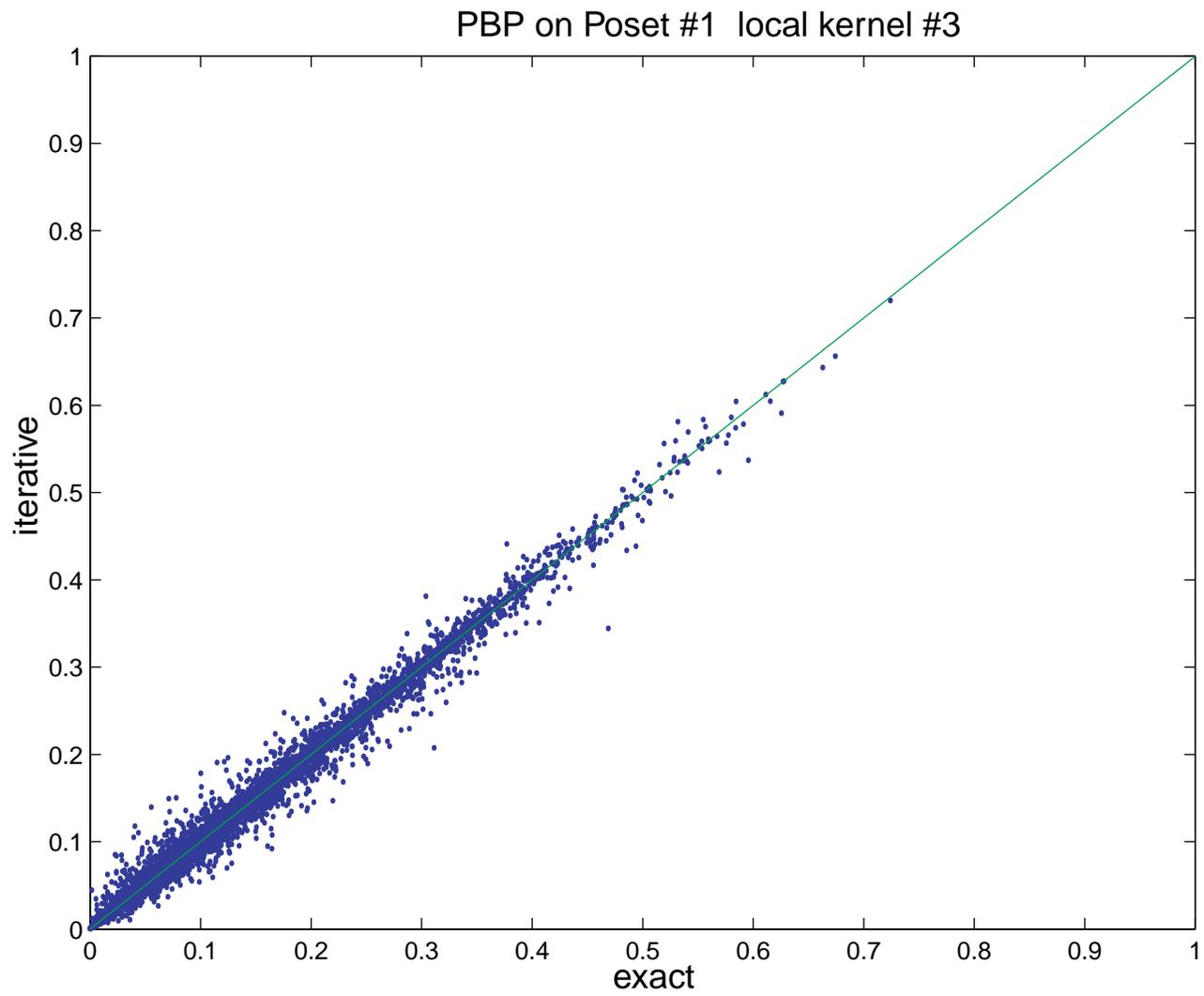
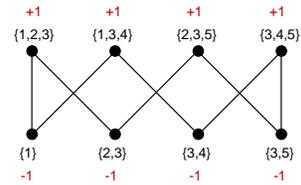
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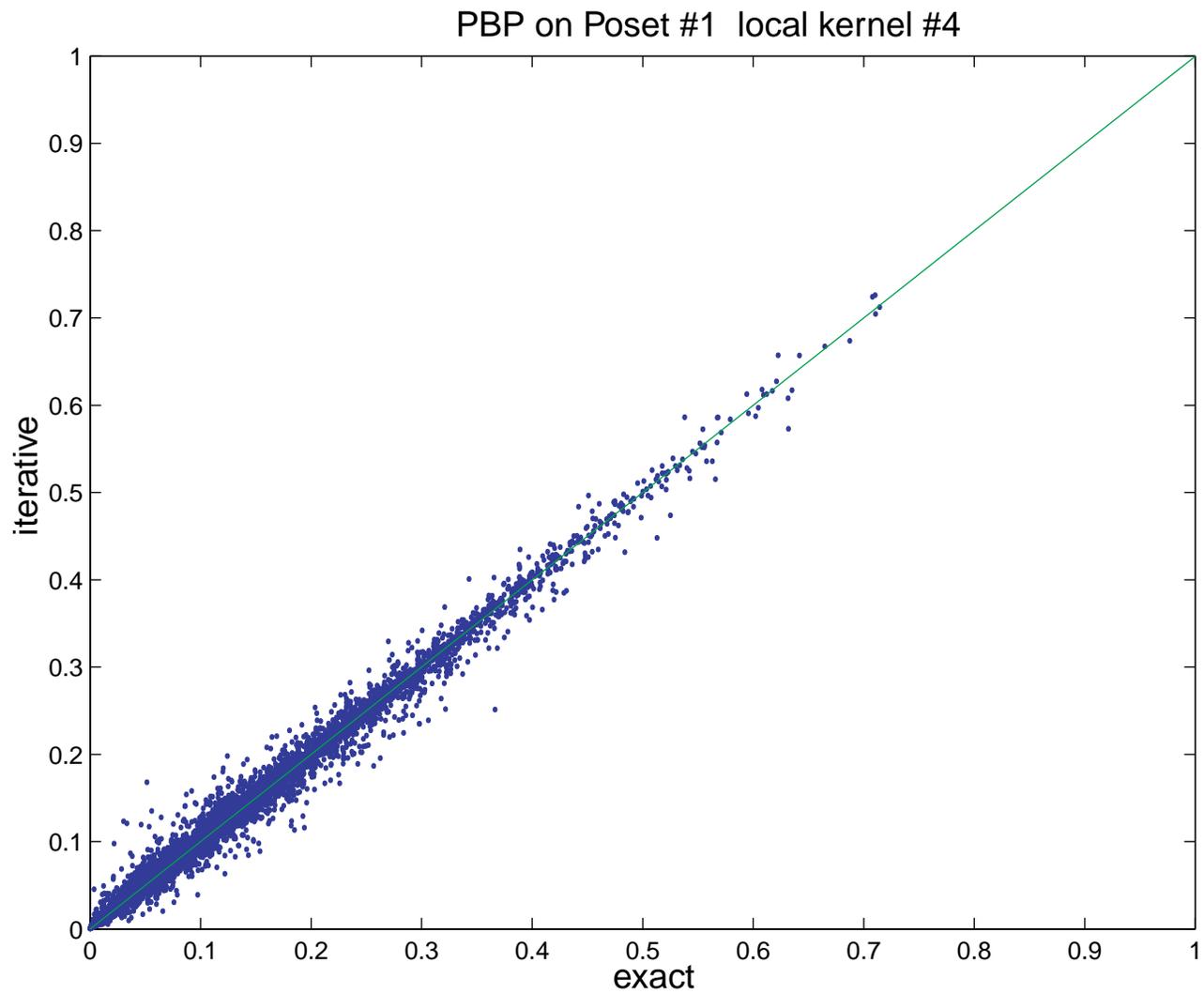
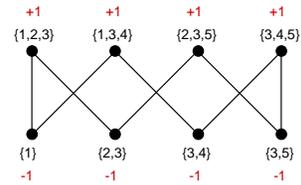
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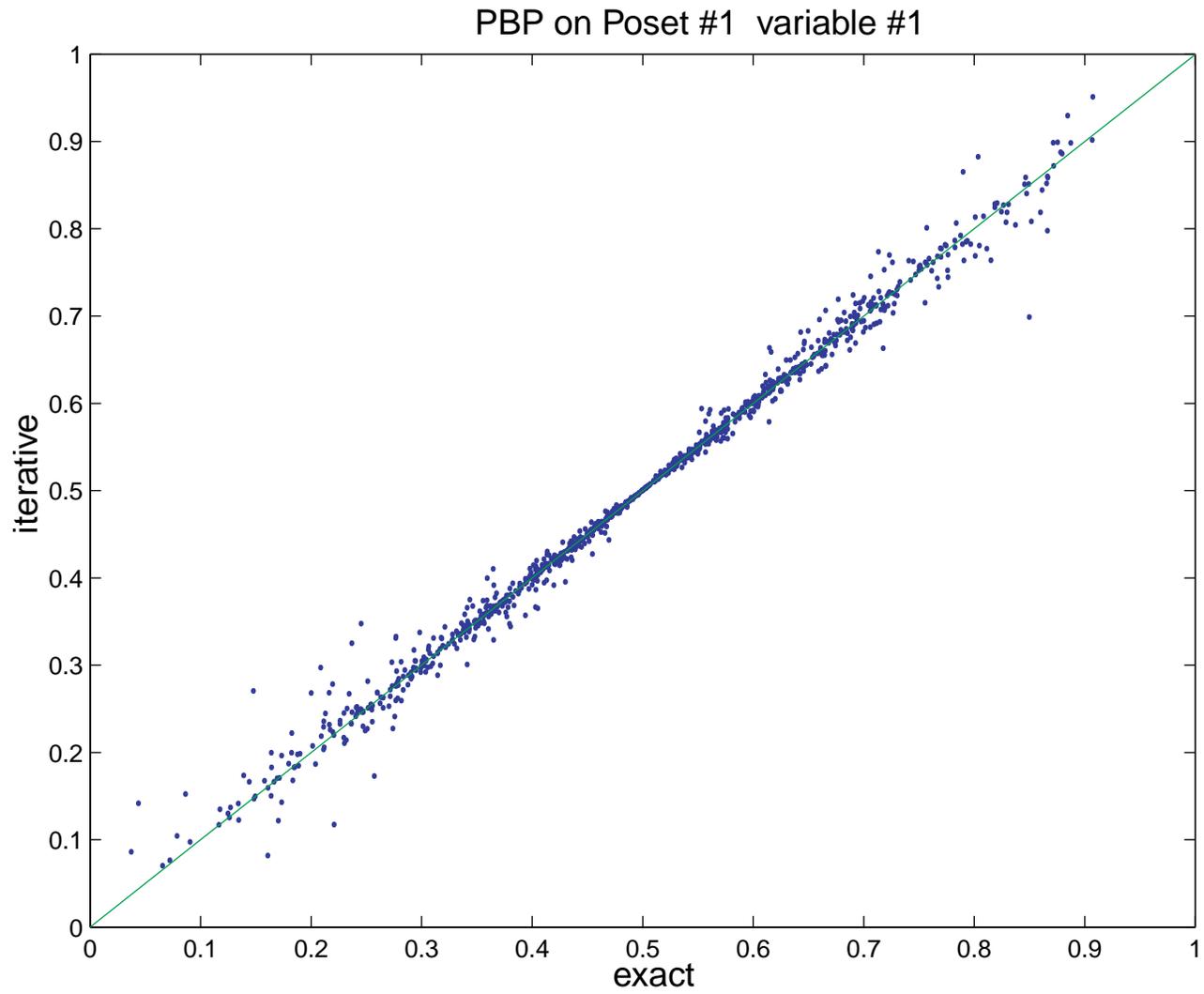
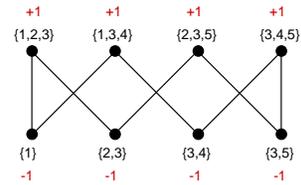
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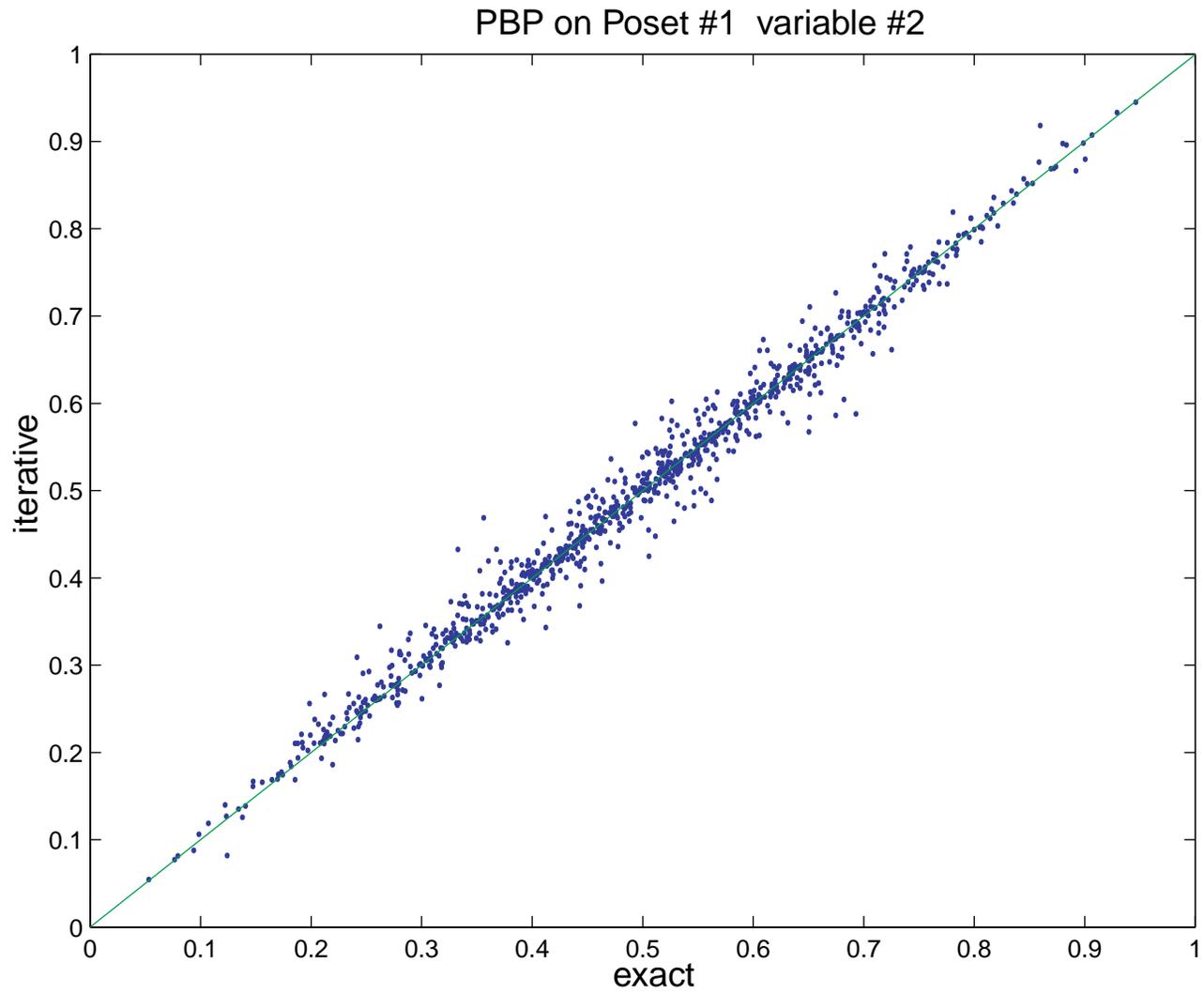
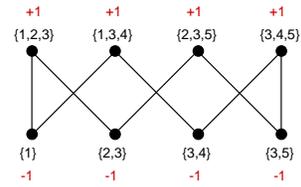
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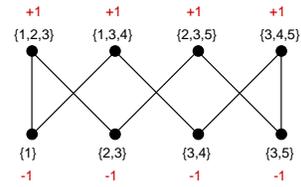
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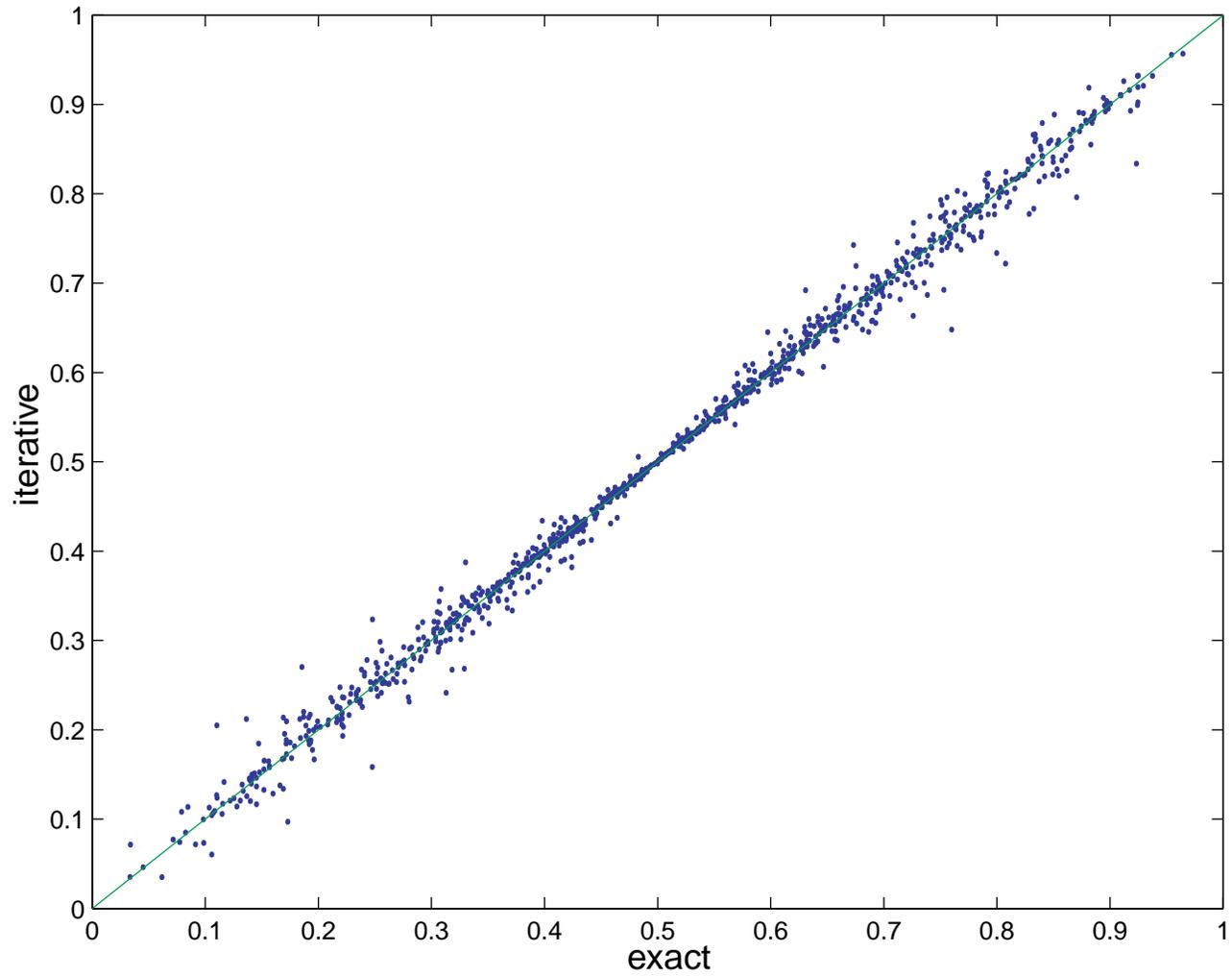
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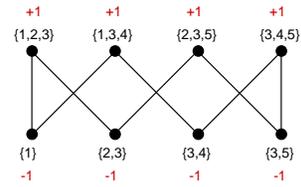
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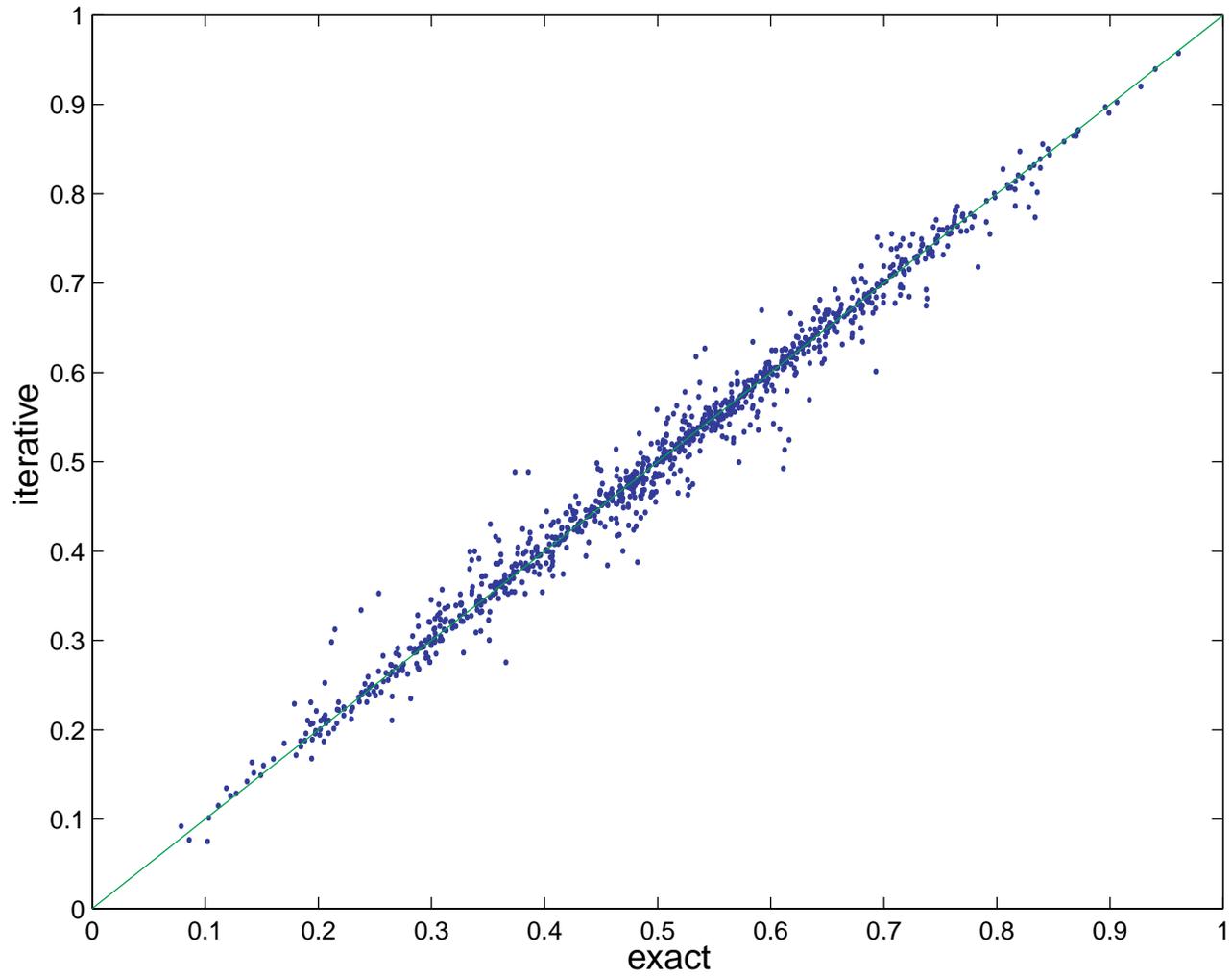
PBP on Poset #1 variable #3



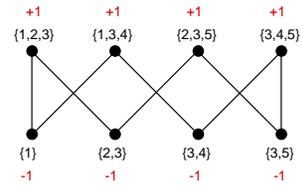
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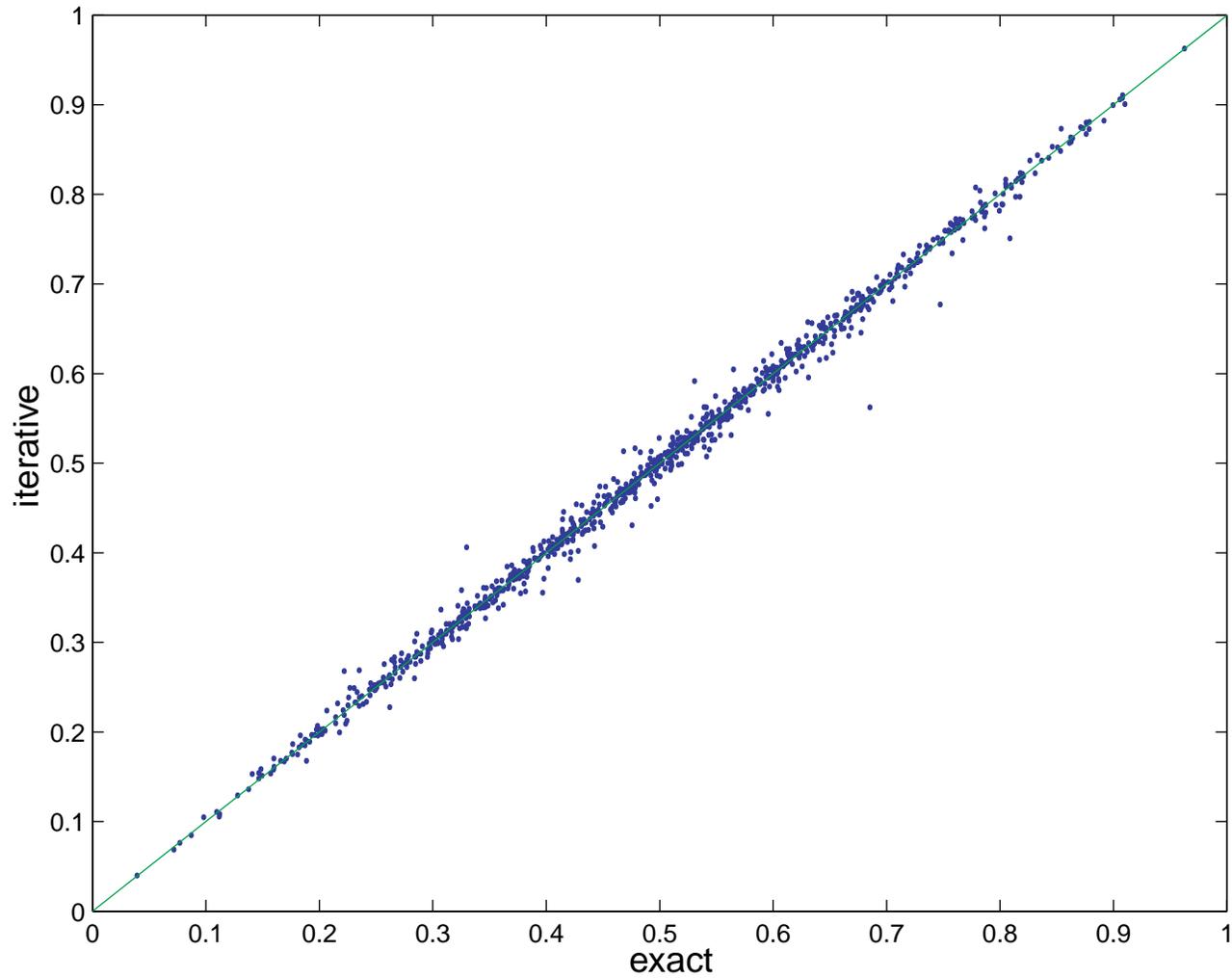
PBP on Poset #1 variable #4



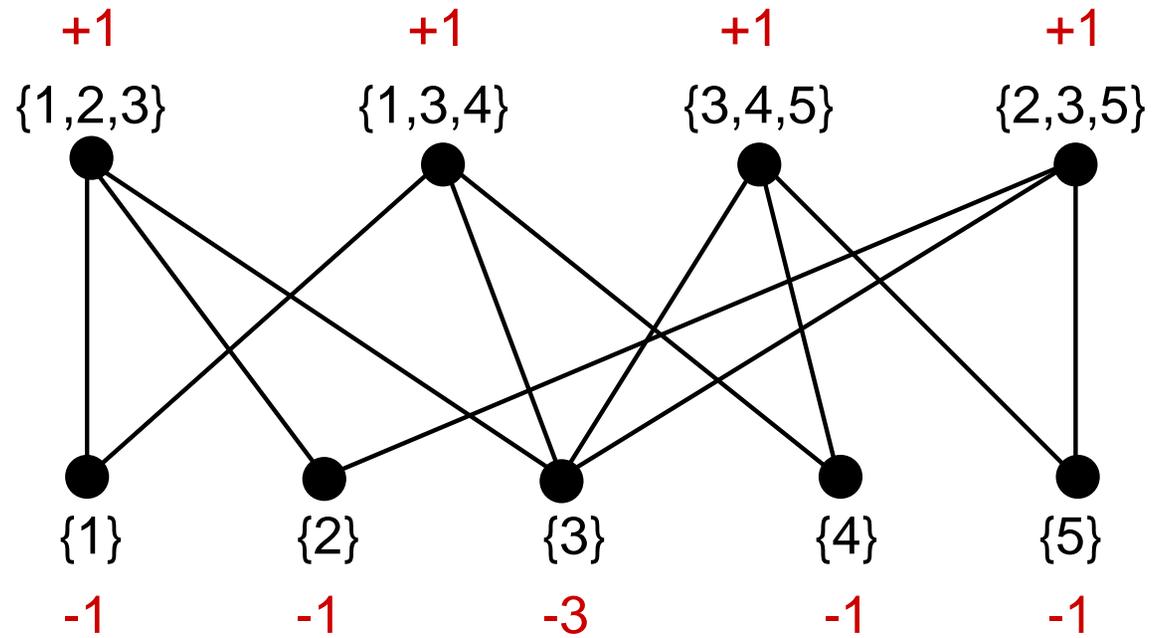
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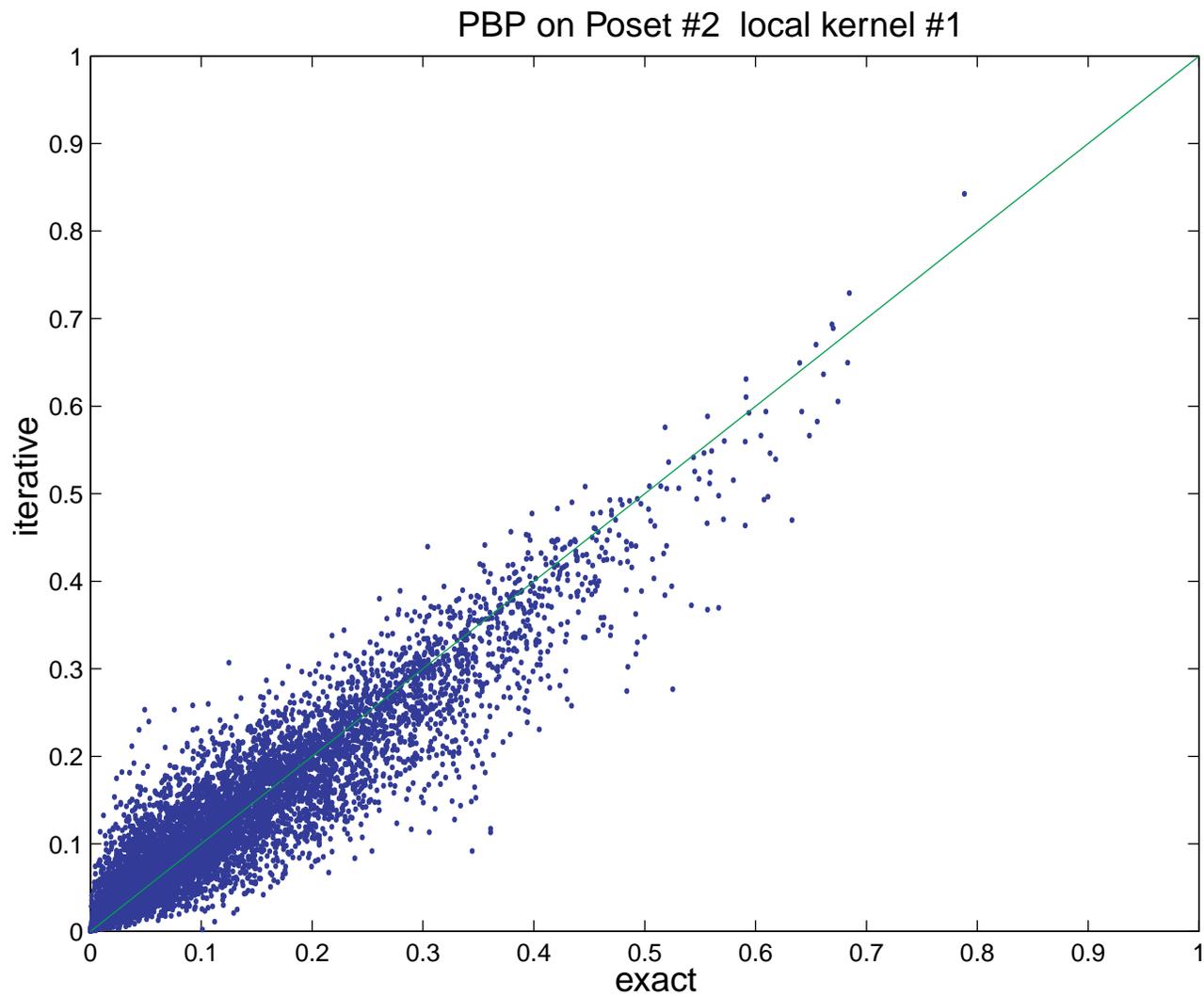
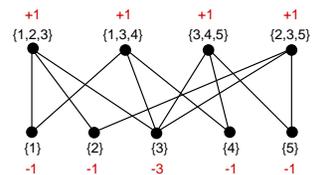
PBP on Poset #1 variable #5



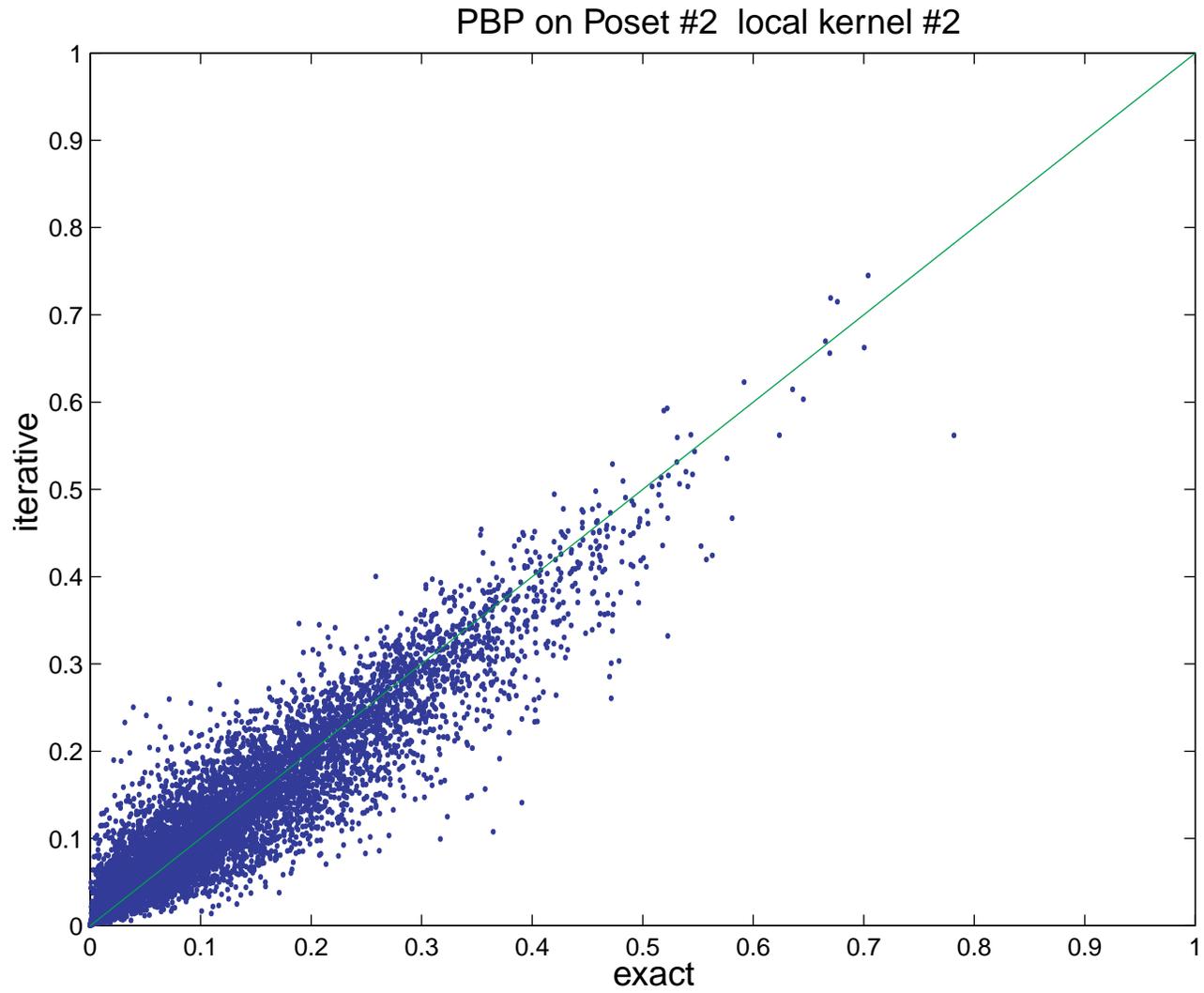
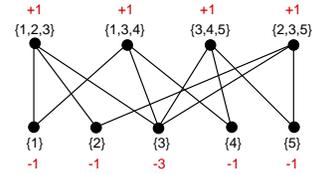
## Poset Number Two (Factor Graph Construction)



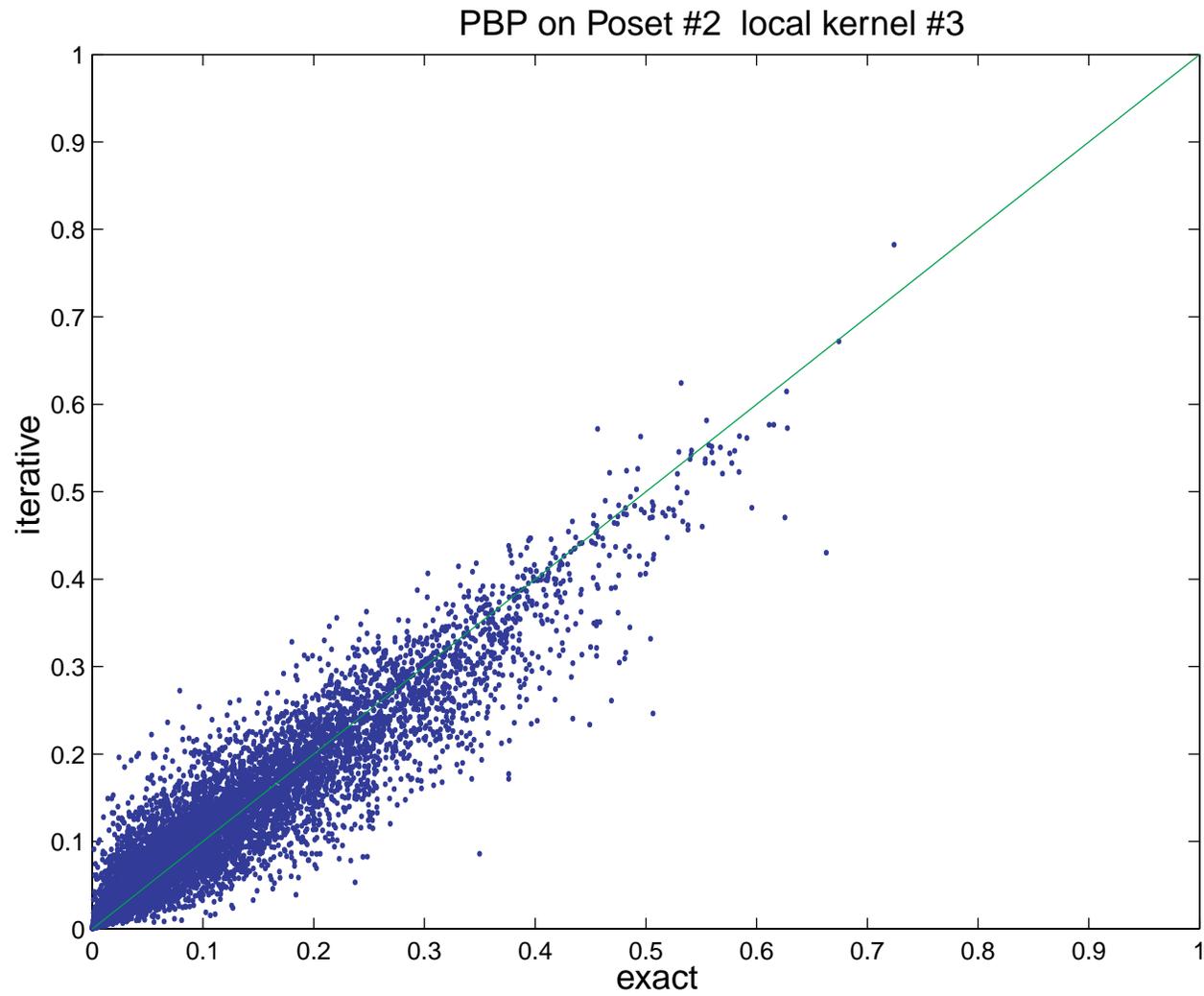
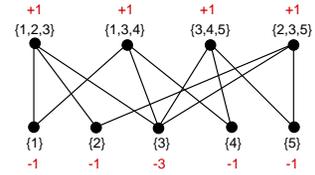
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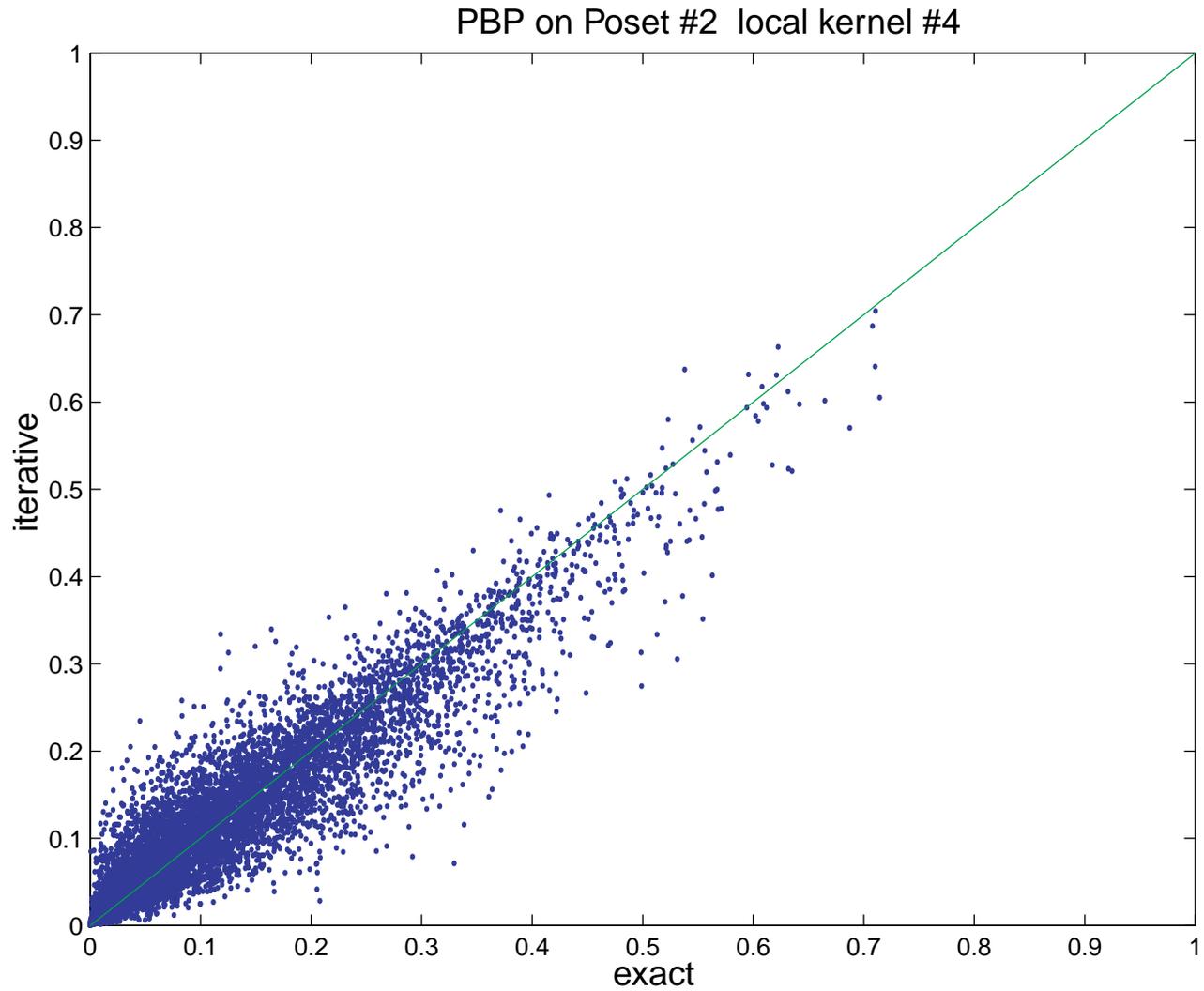
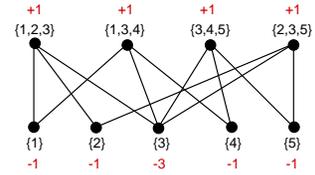
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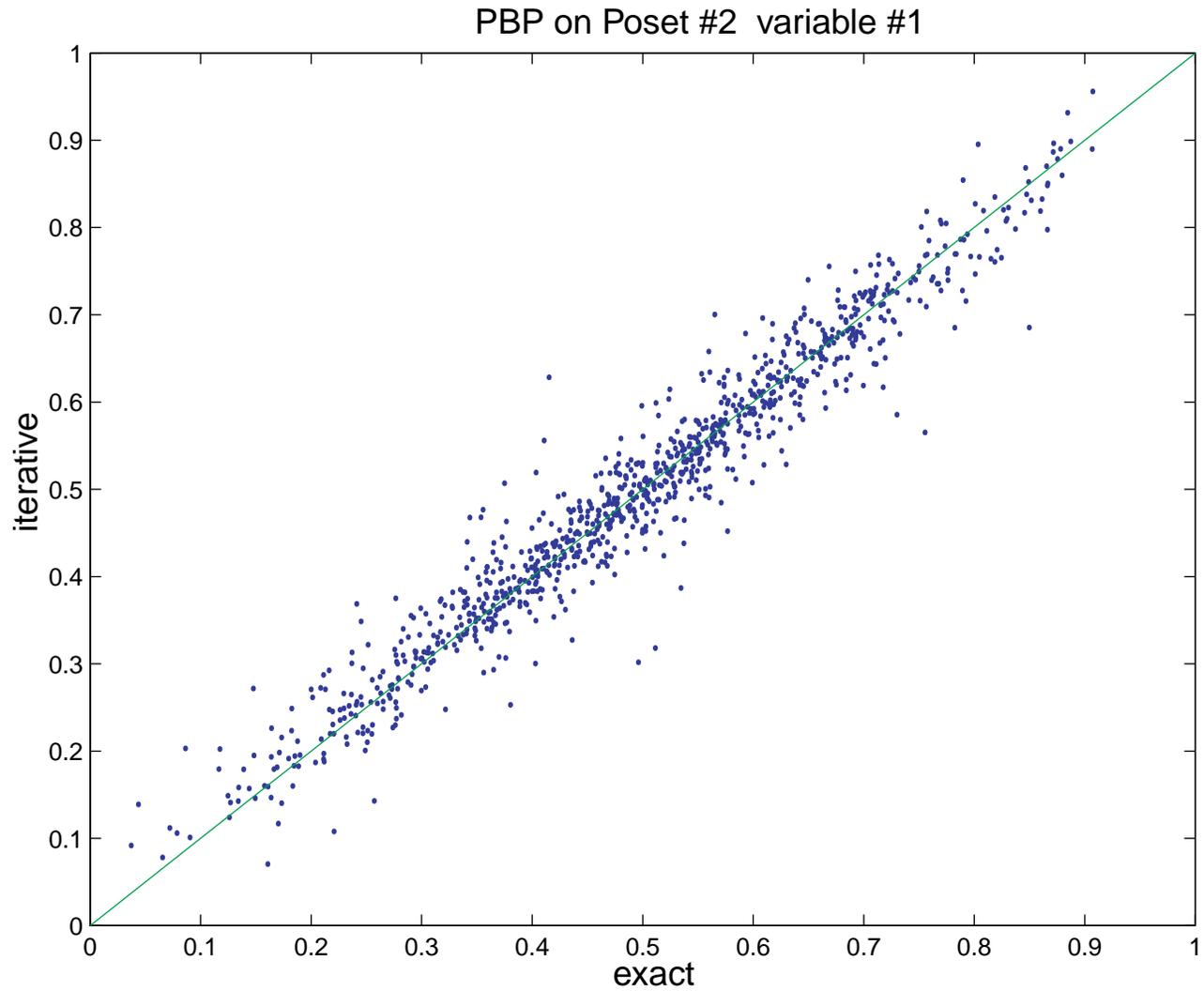
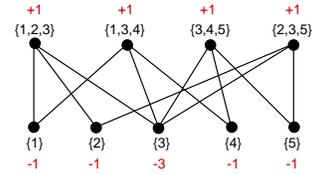
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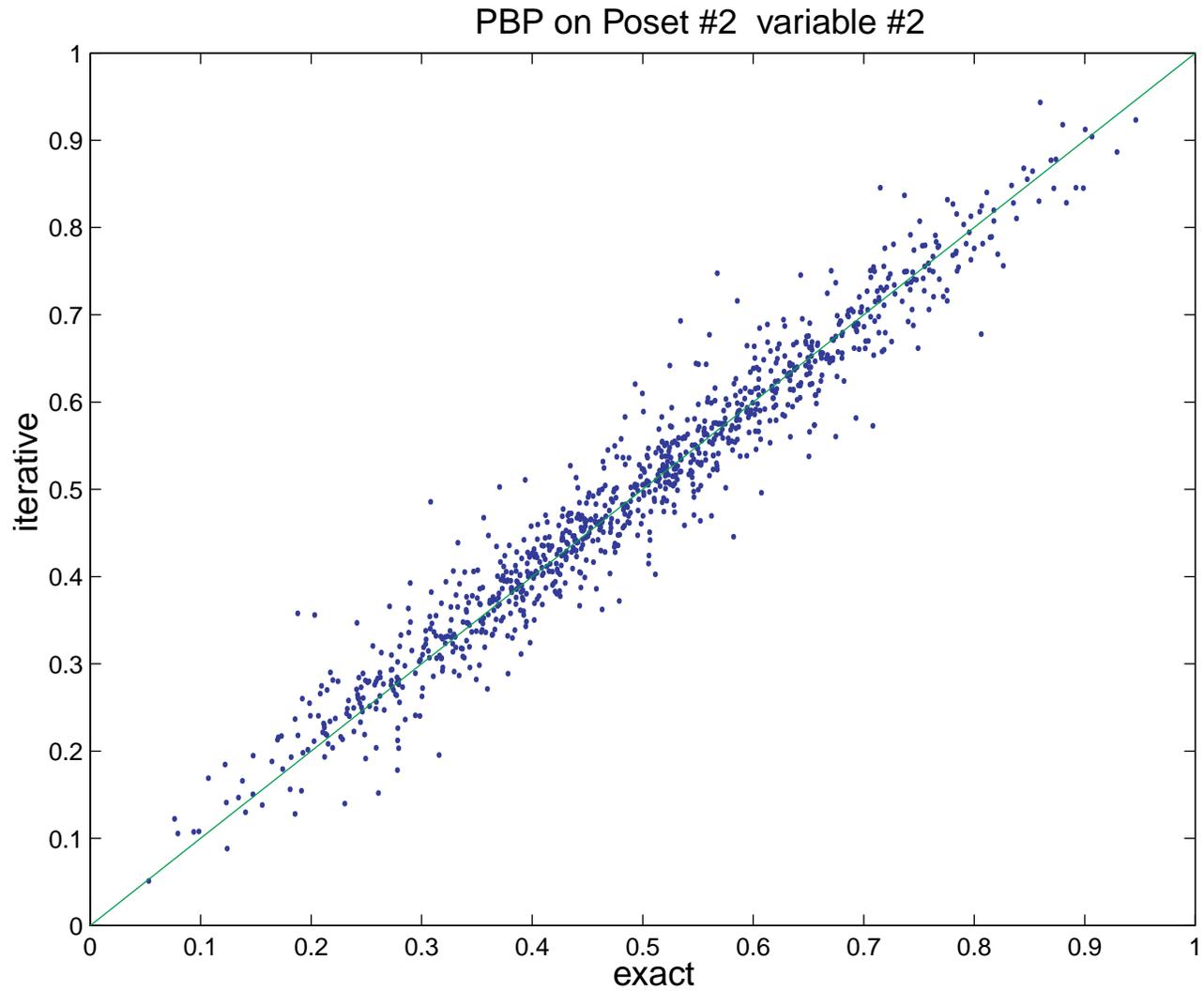
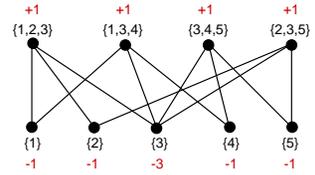
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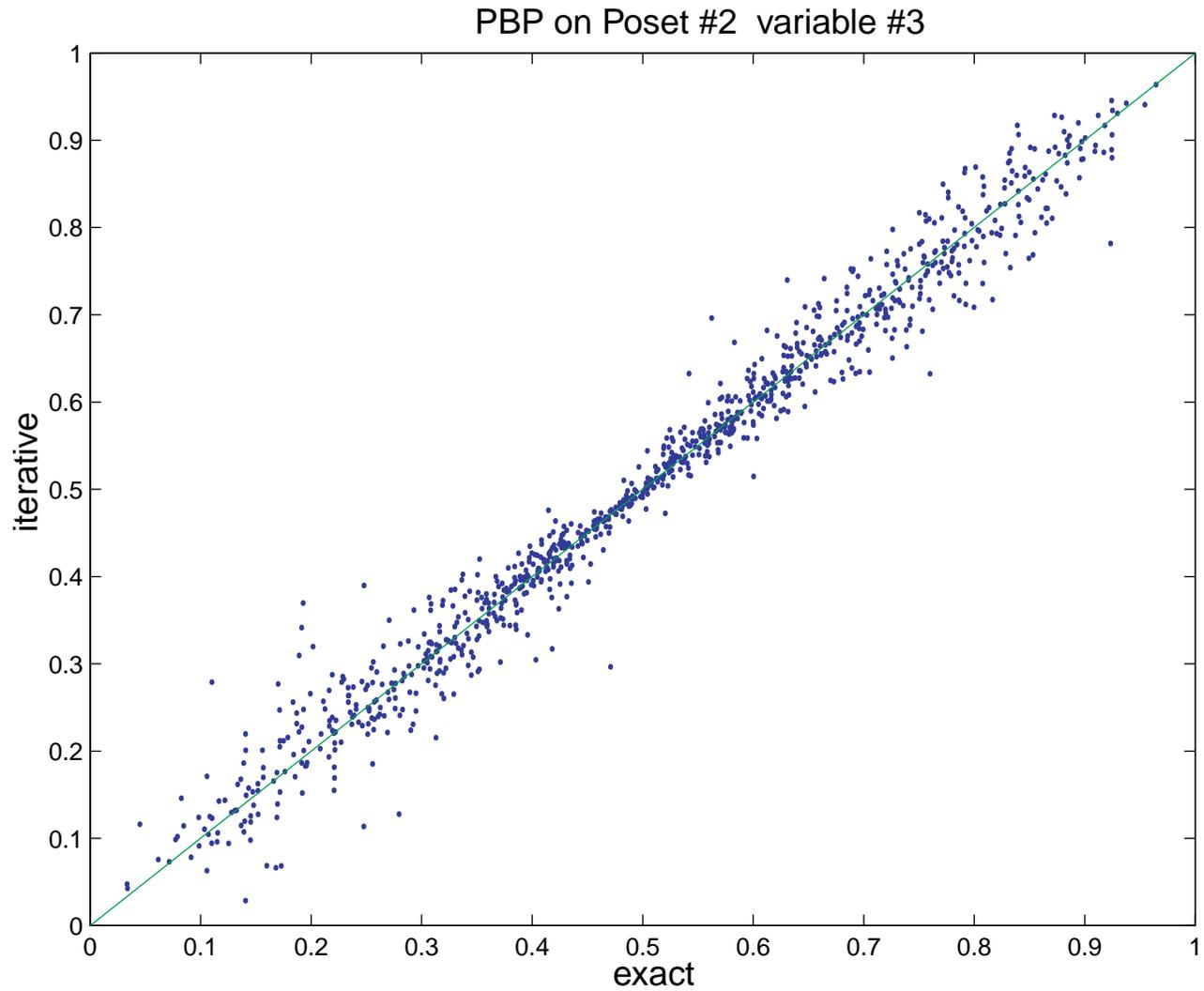
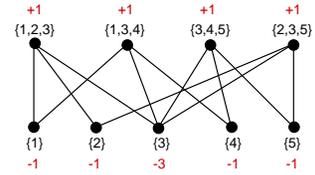
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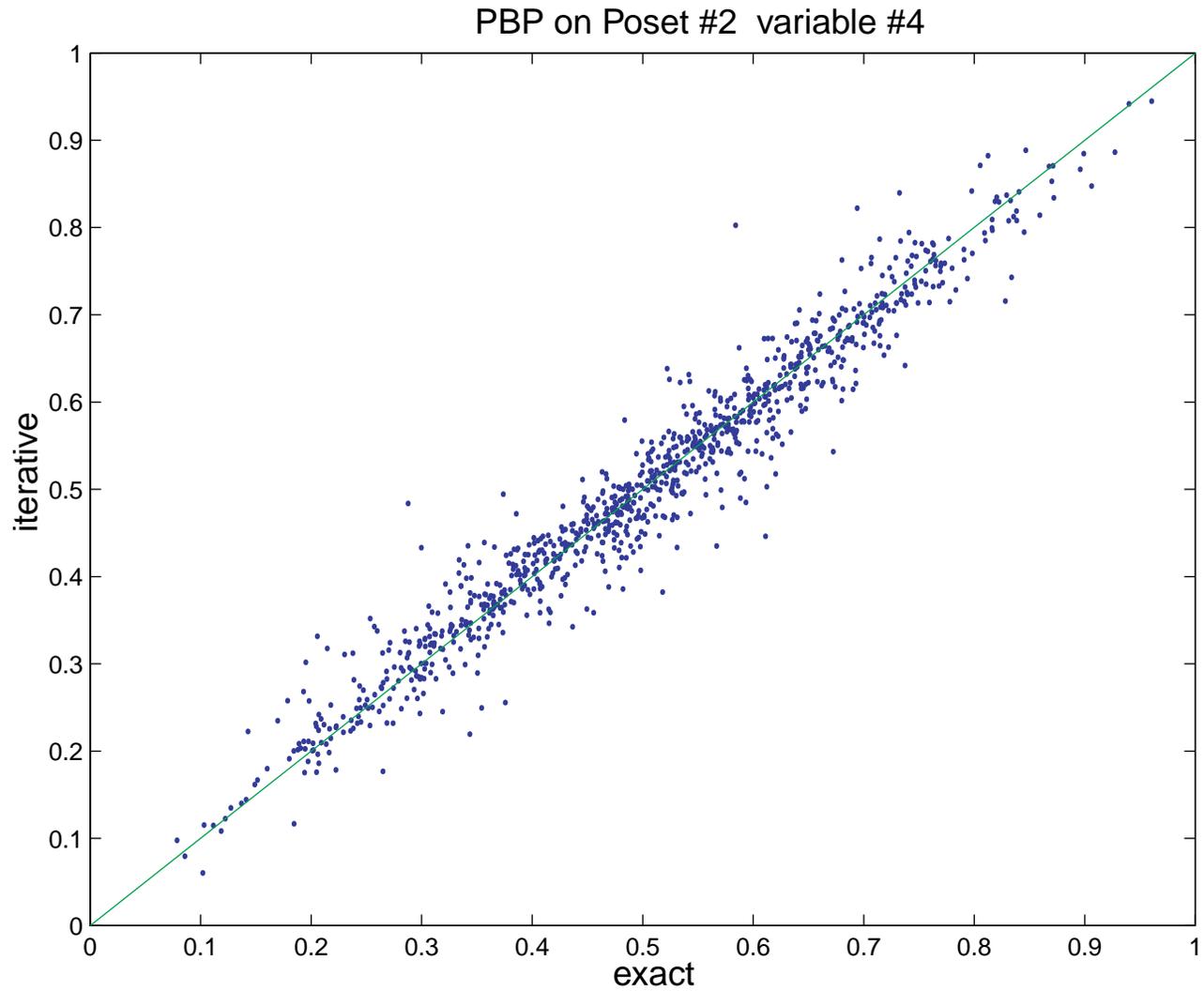
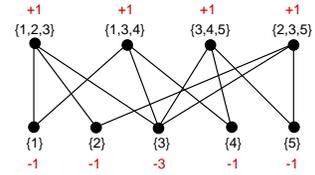
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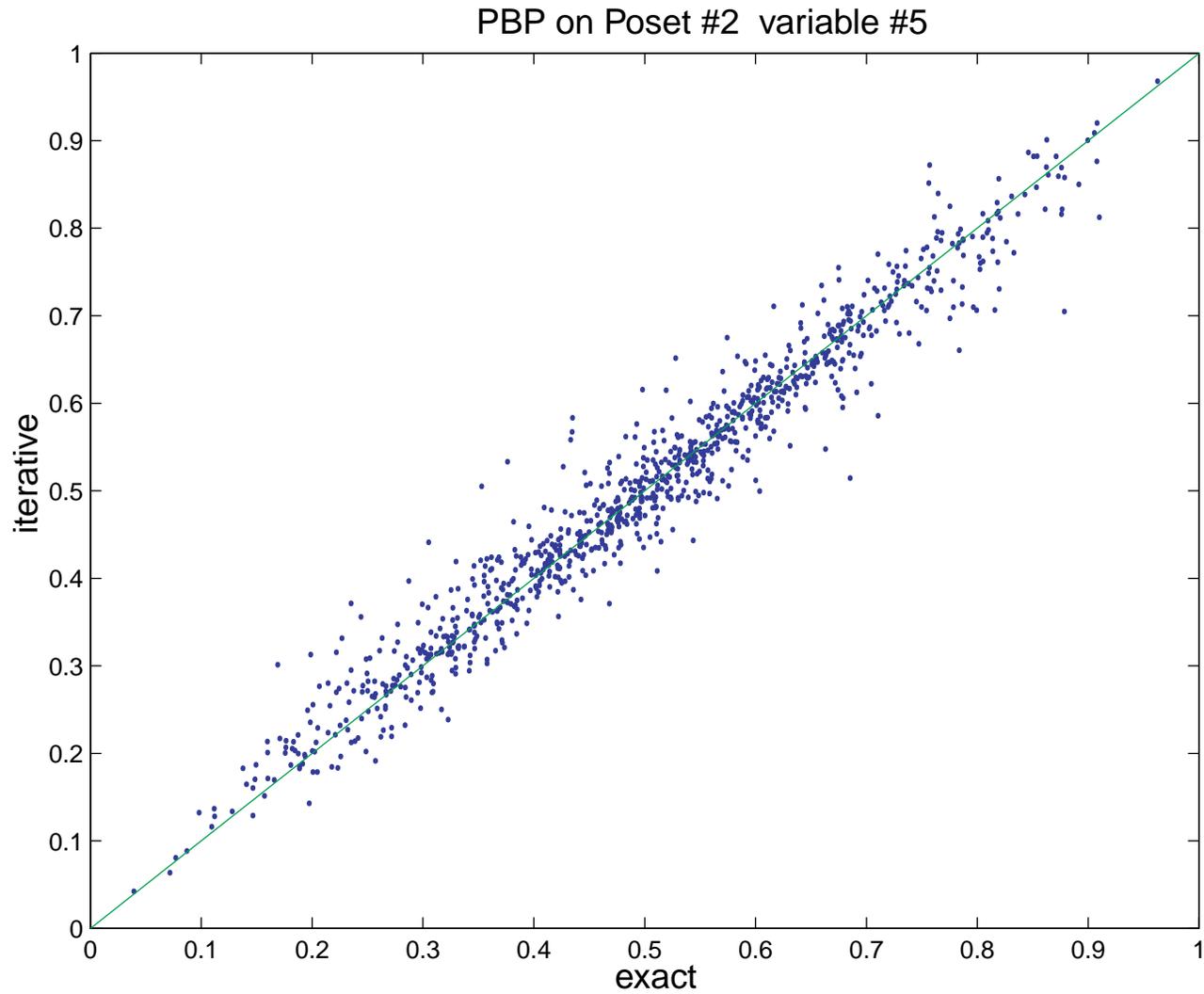
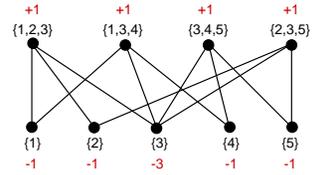
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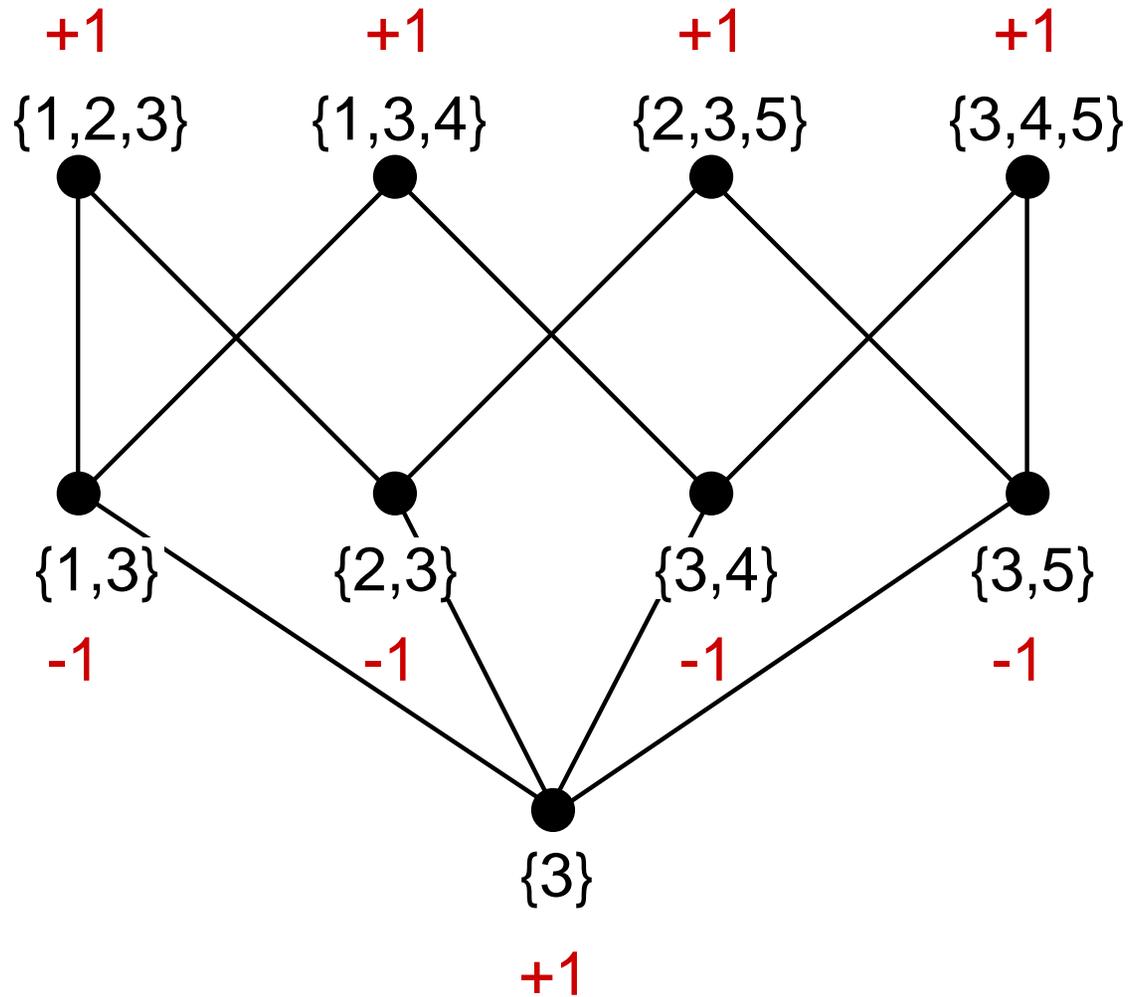
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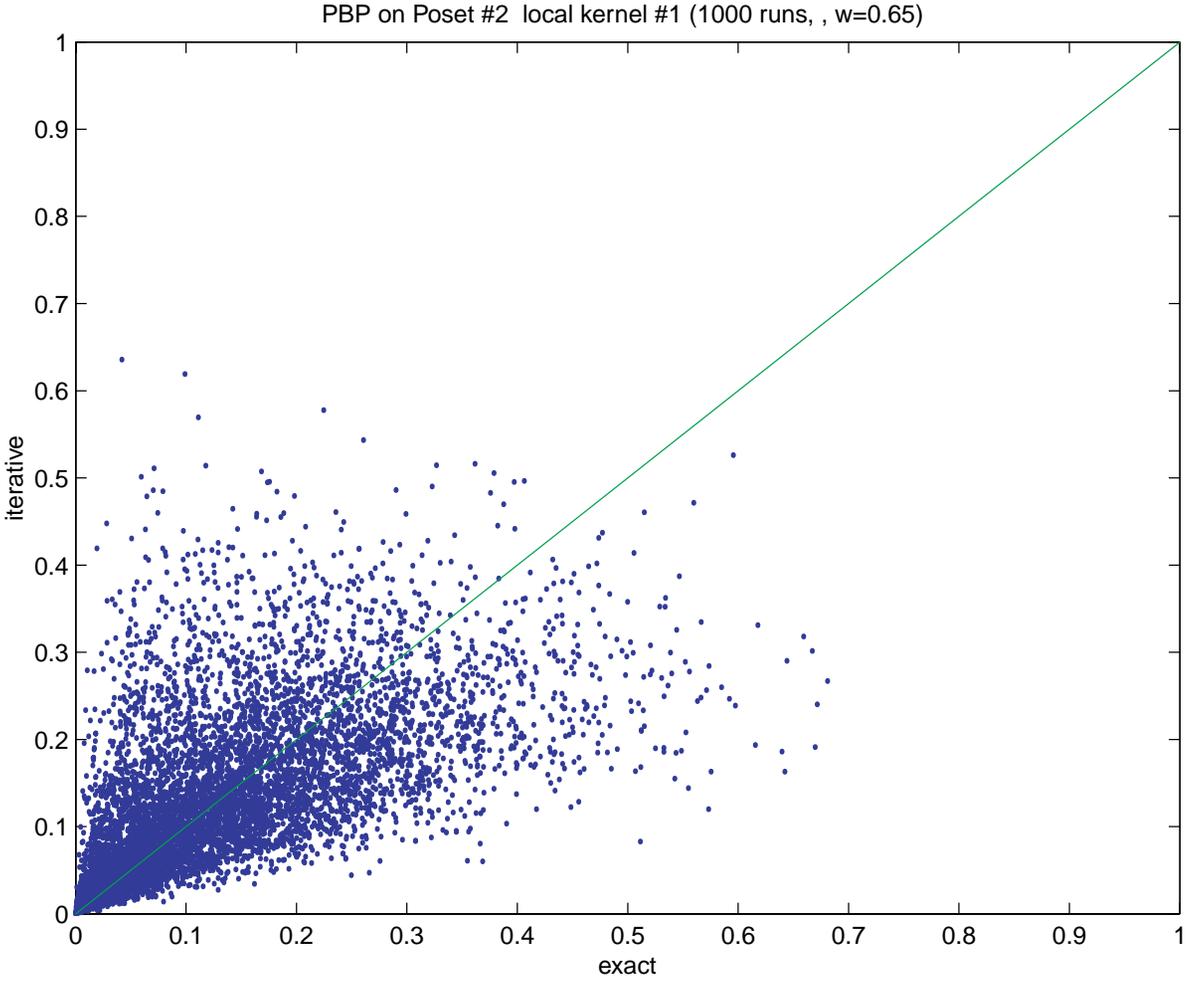
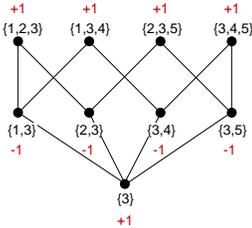
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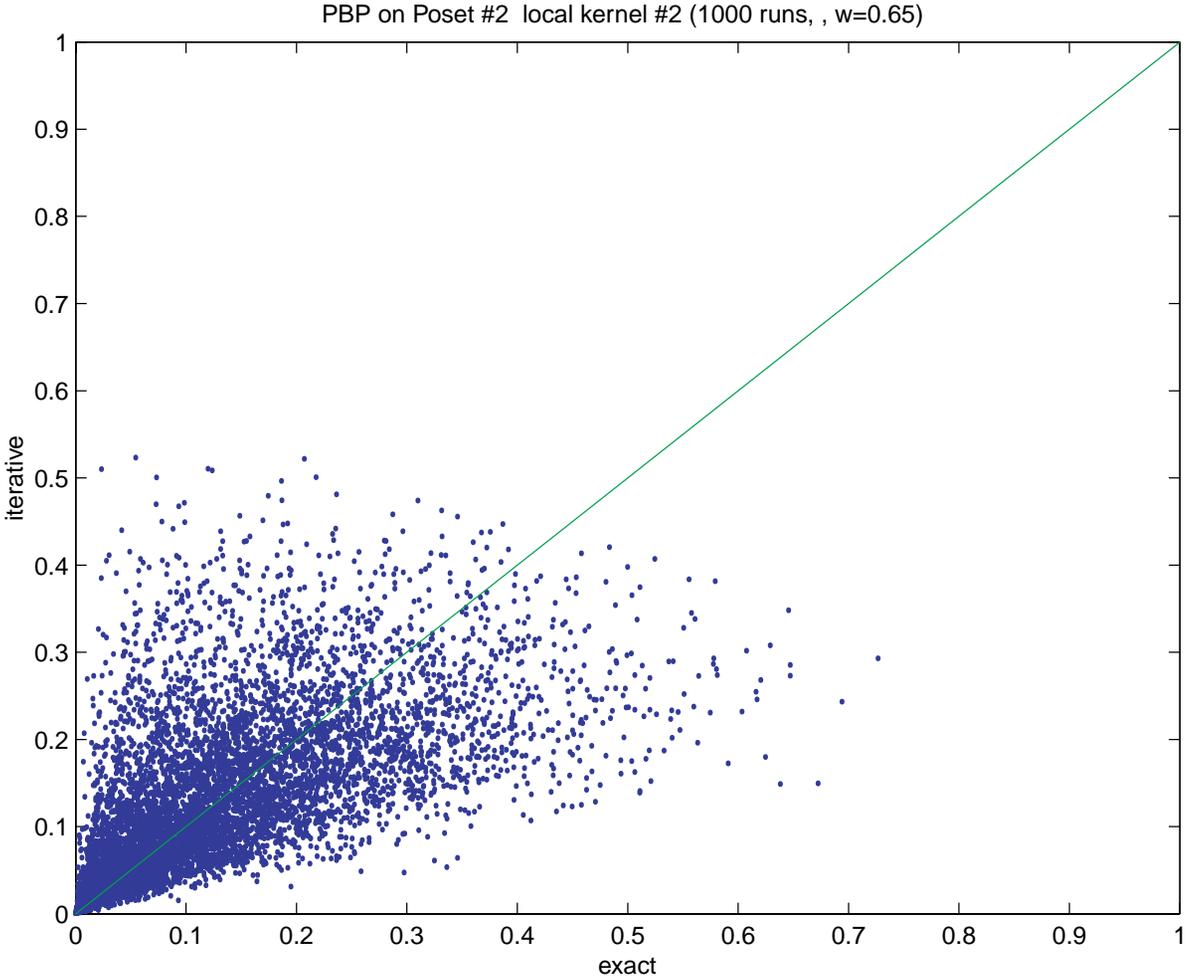
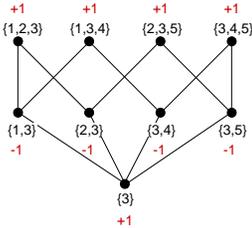
# Poset Number Three (Cluster Variational Method)



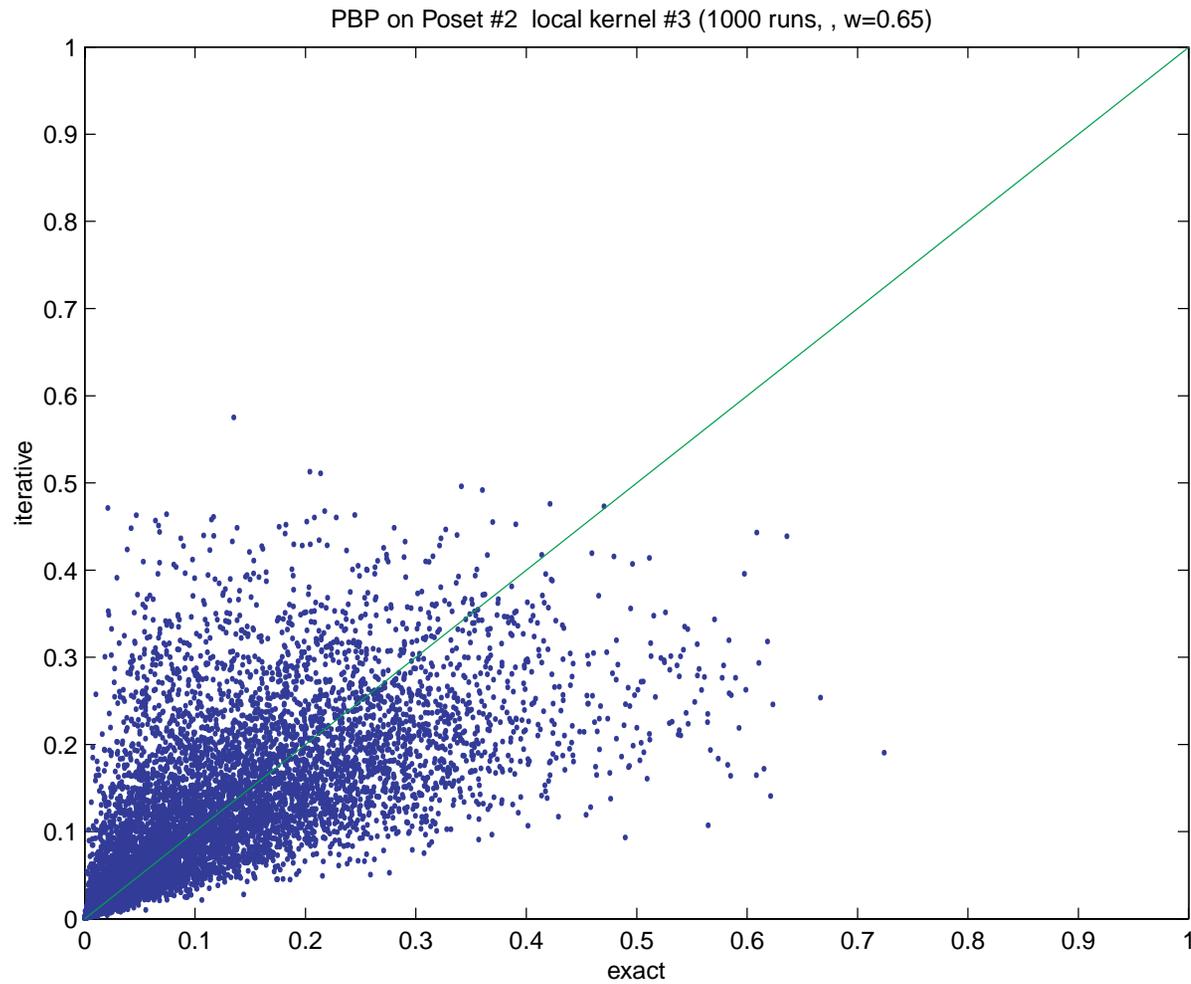
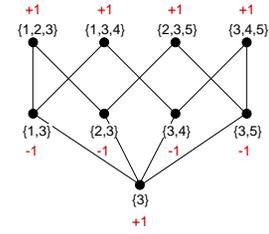
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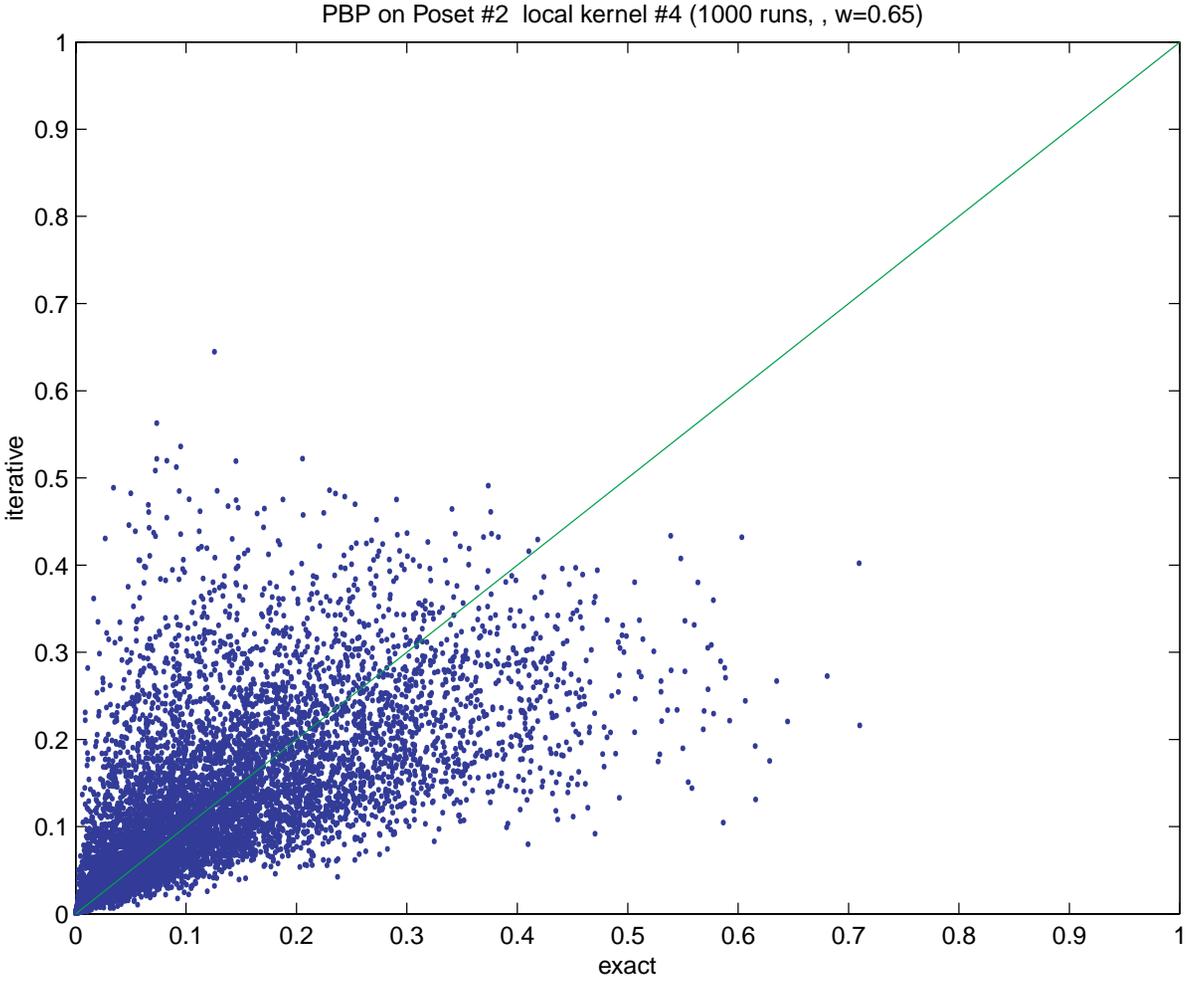
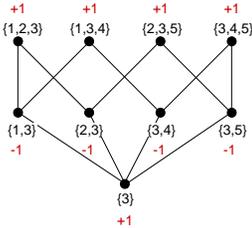
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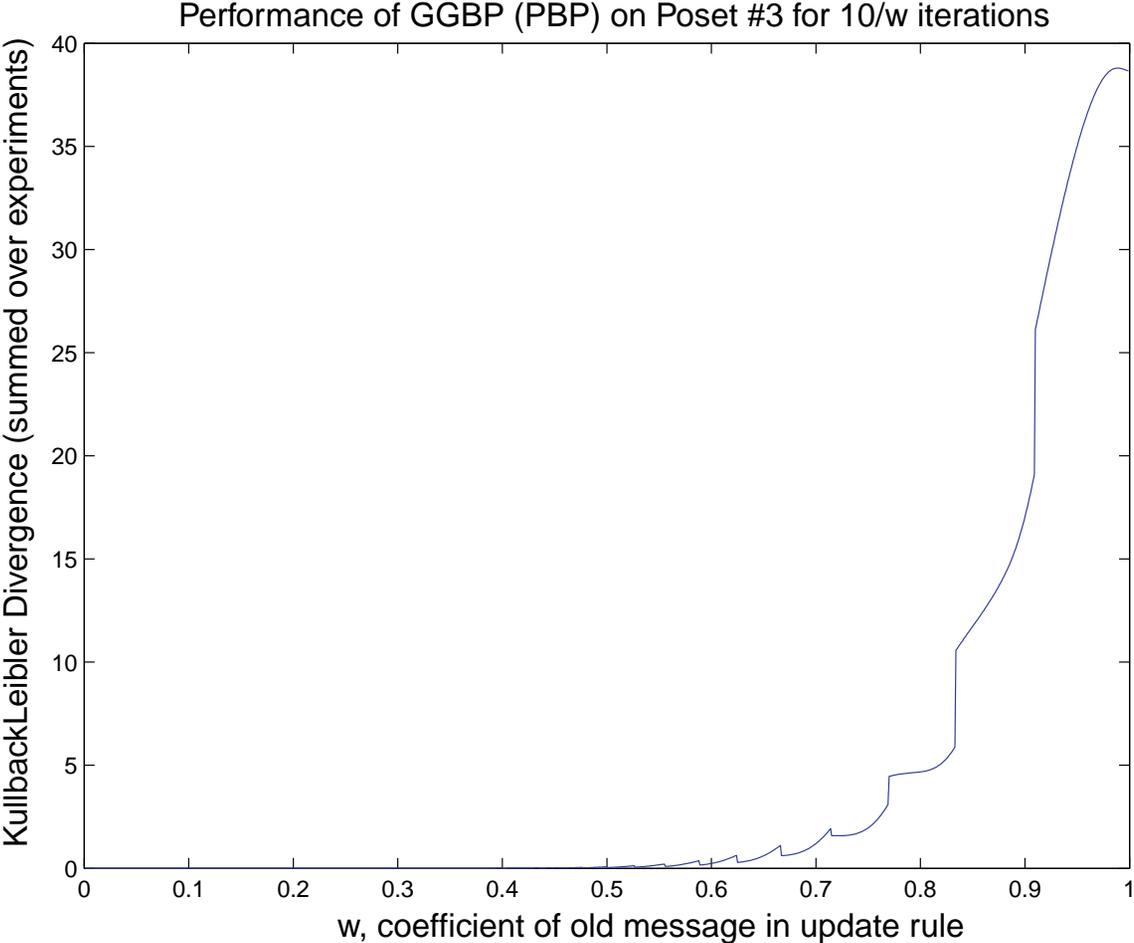
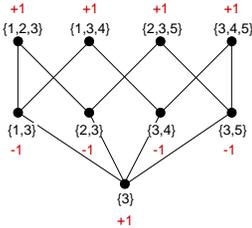
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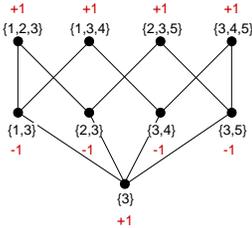
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$$y_{n+1} = y_n^{1-w} F(y_n)^w \quad \text{for } 0 < w < 1.$$

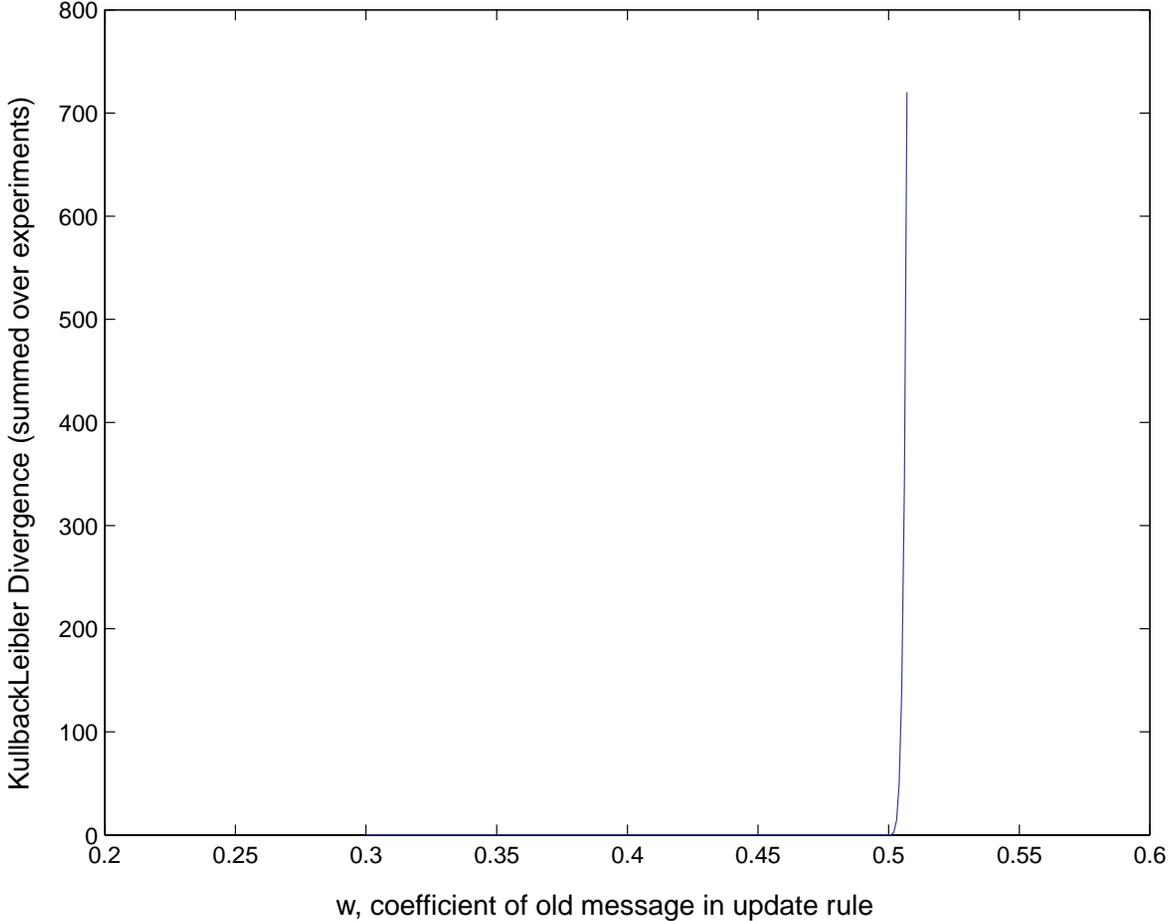
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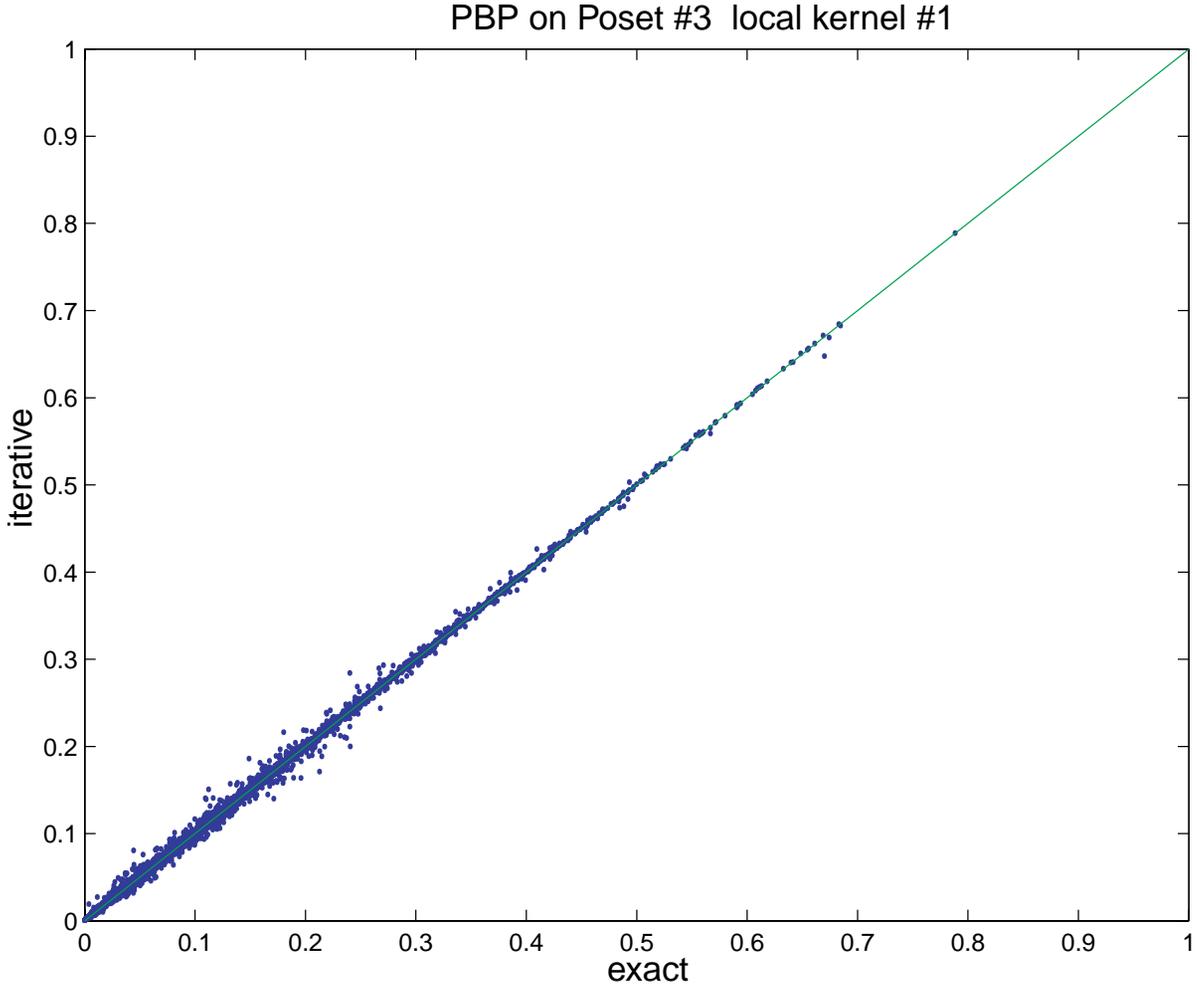
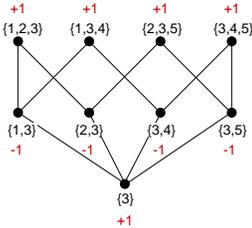
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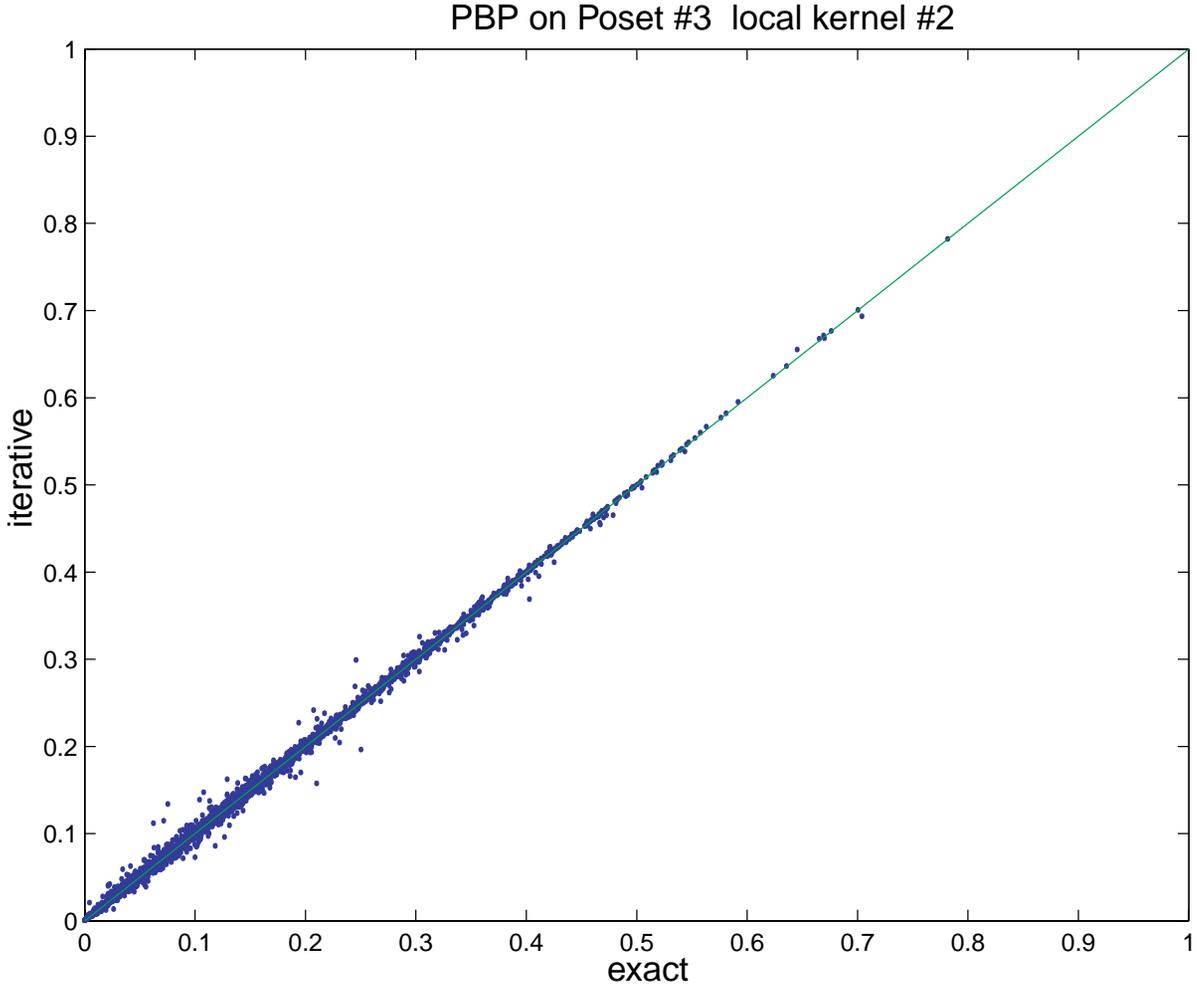
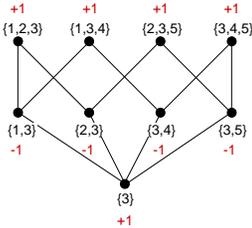
Performance of GGBP (PBP) on Poset #3 for 1000/w iterations (on [.3,.6])



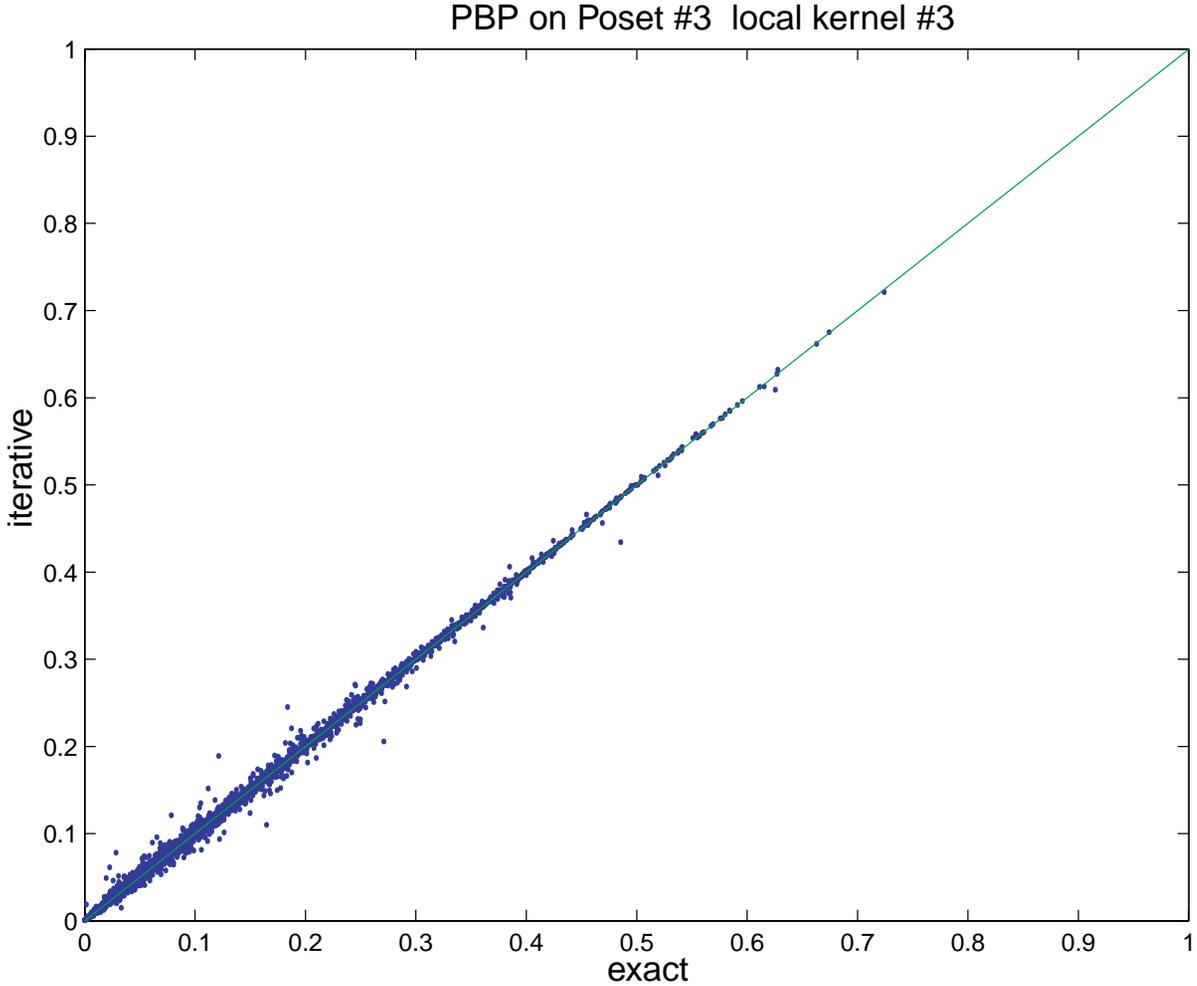
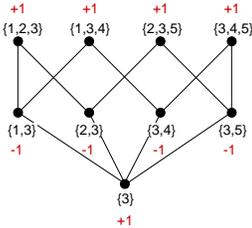
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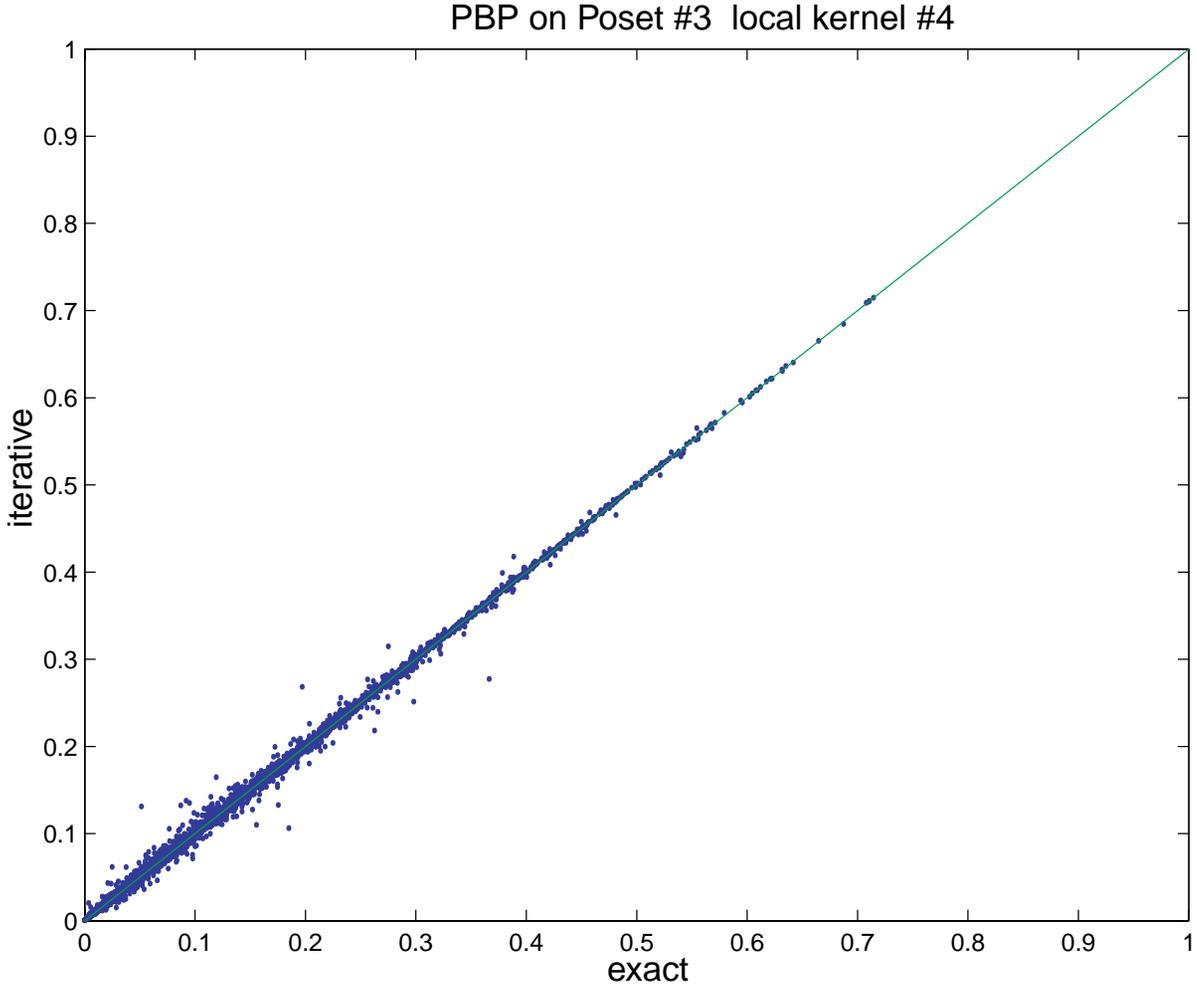
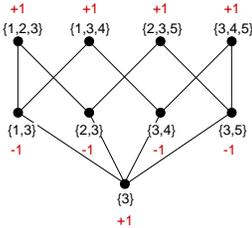
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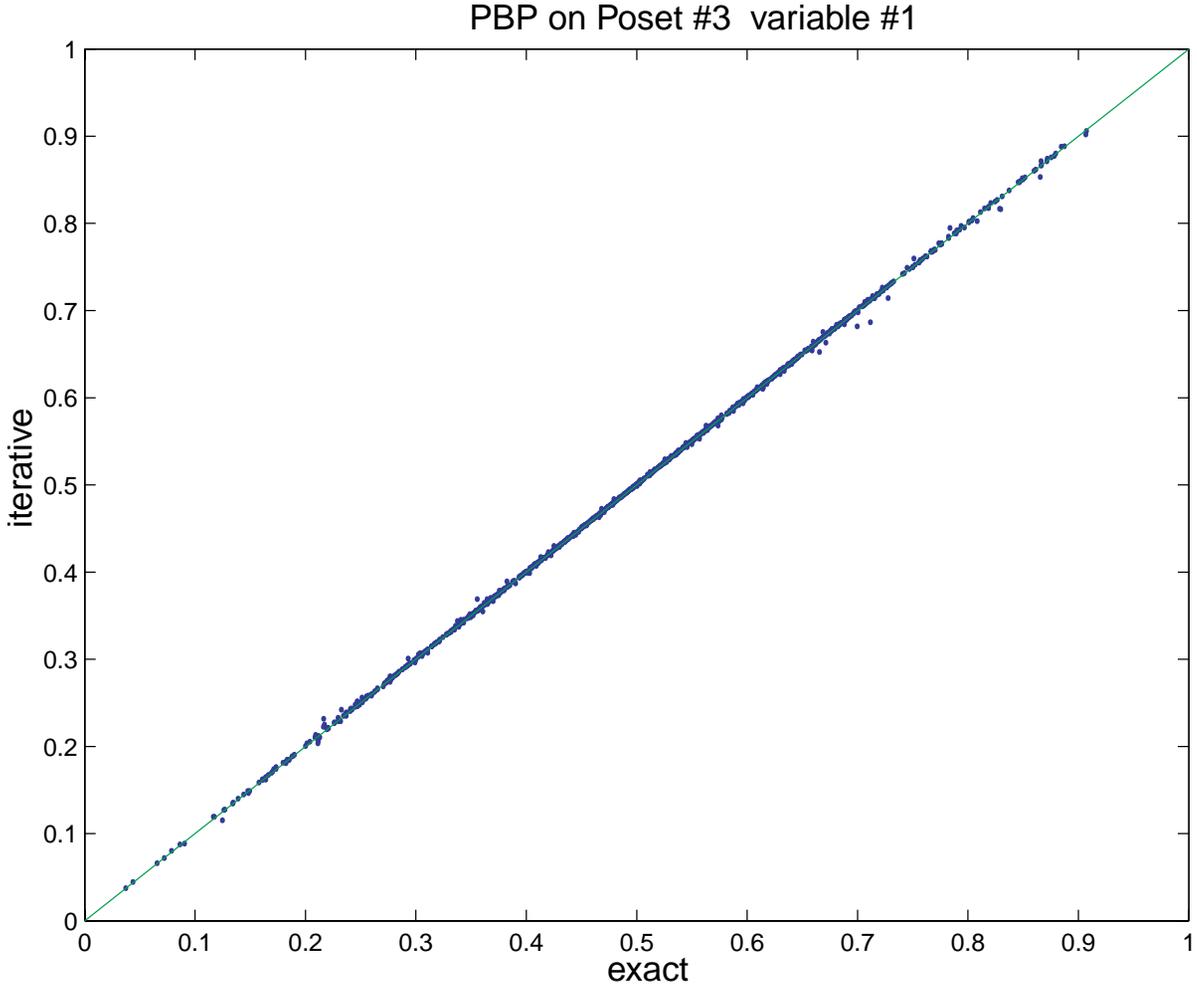
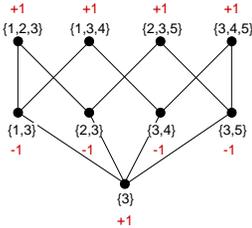
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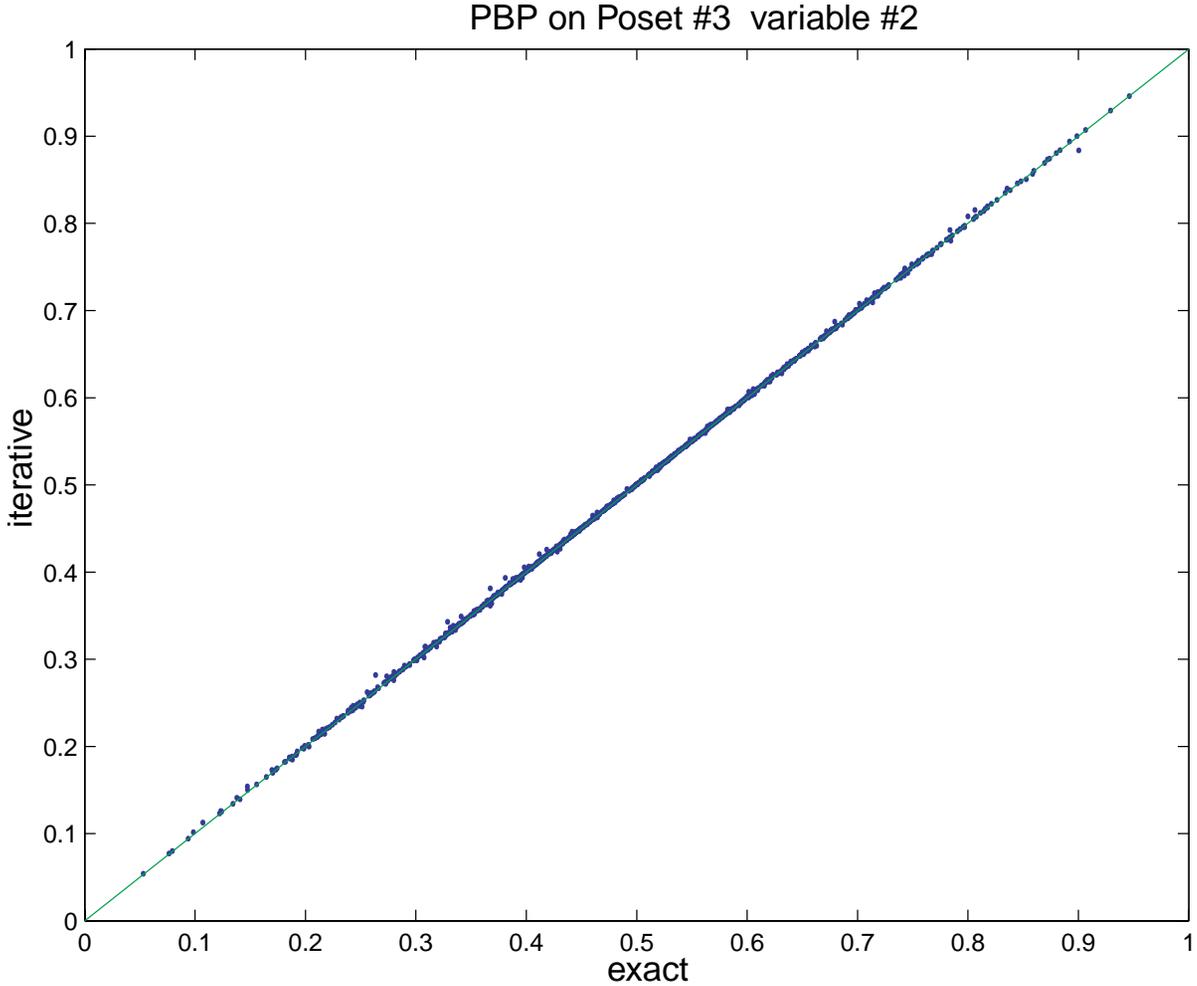
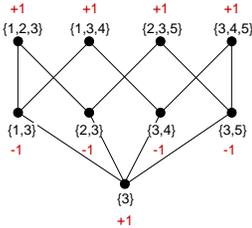
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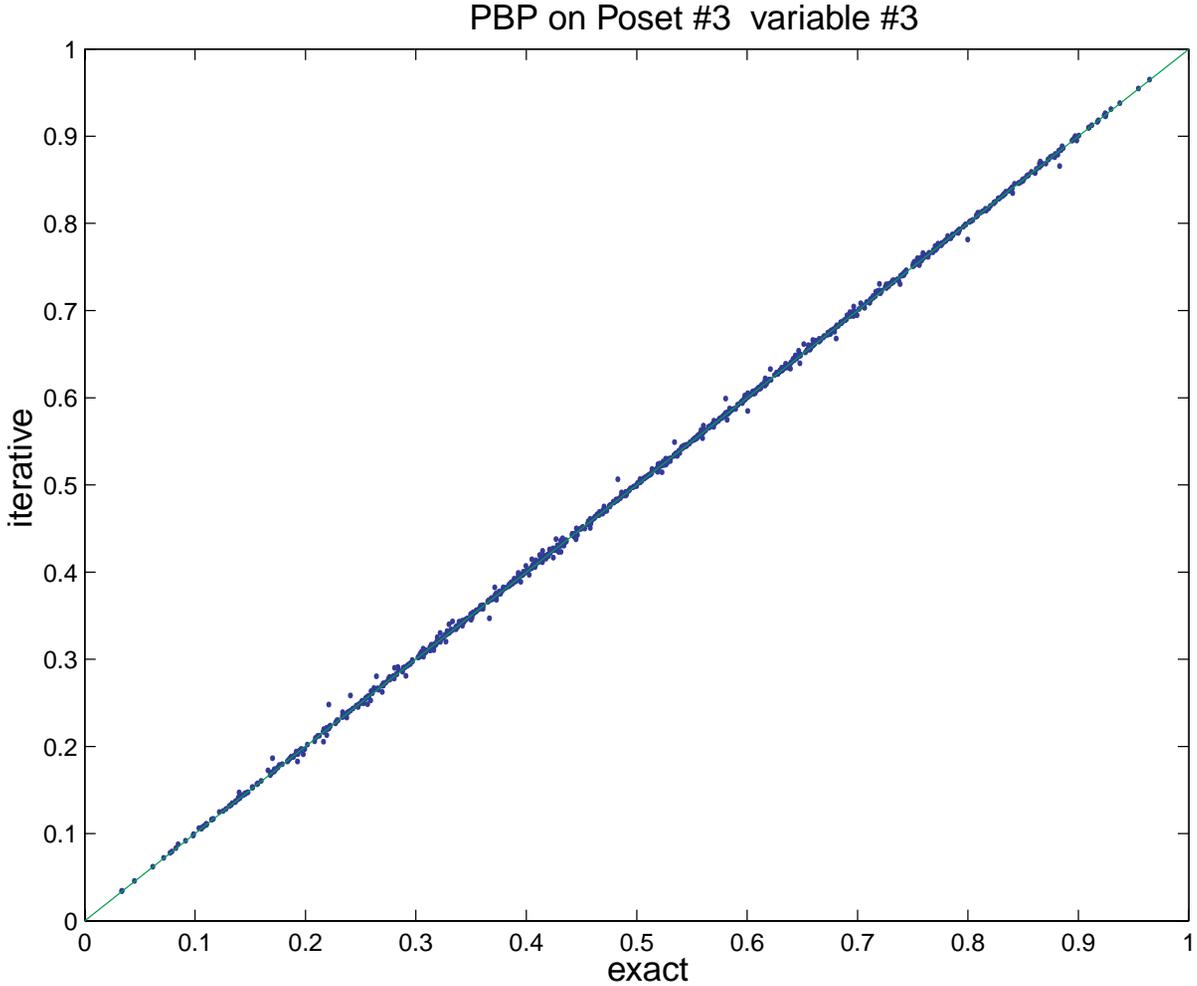
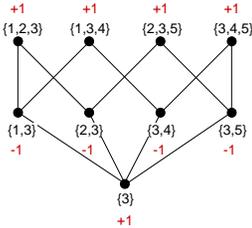
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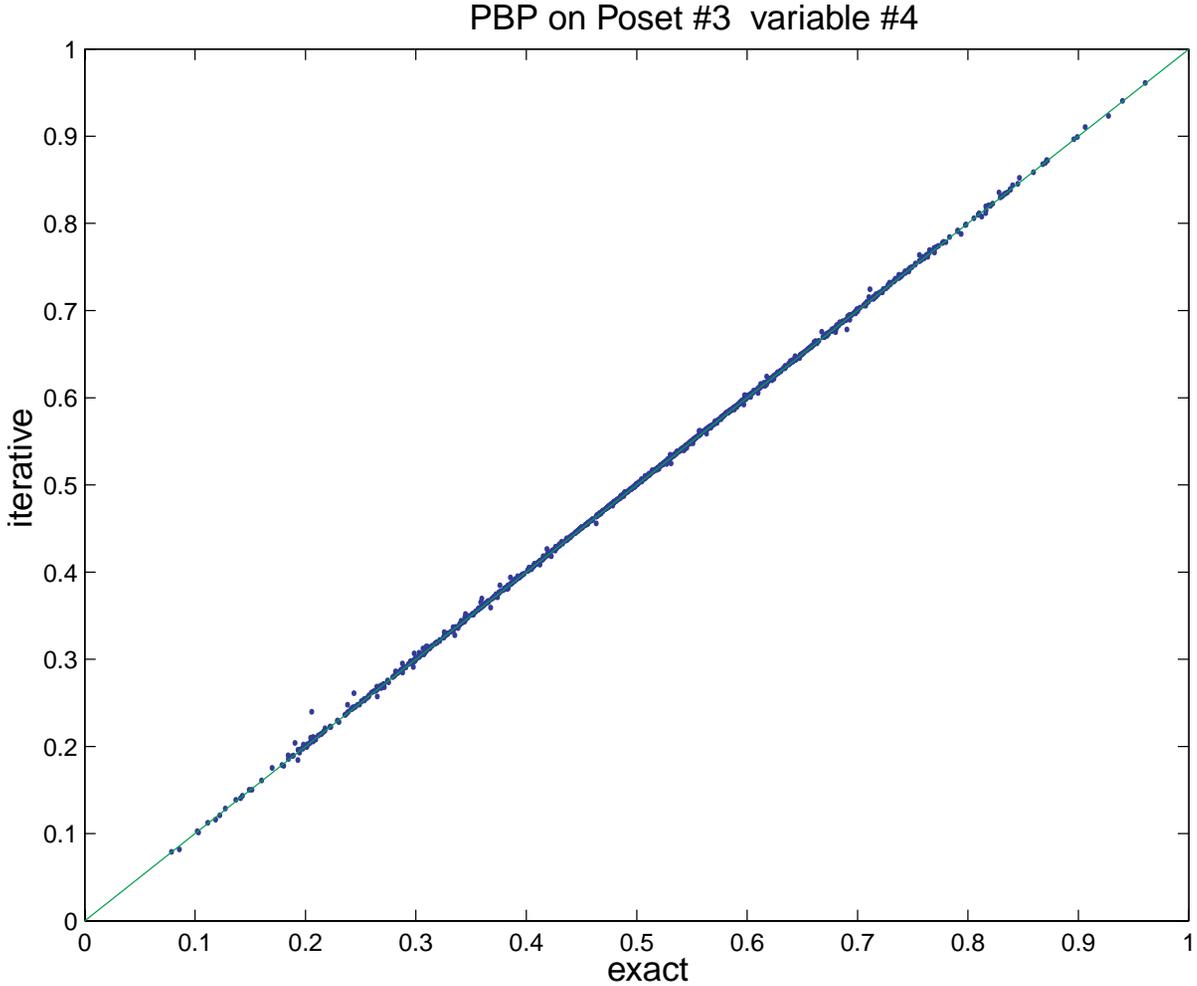
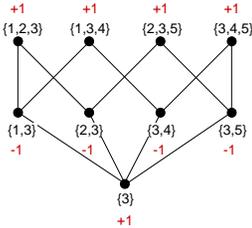
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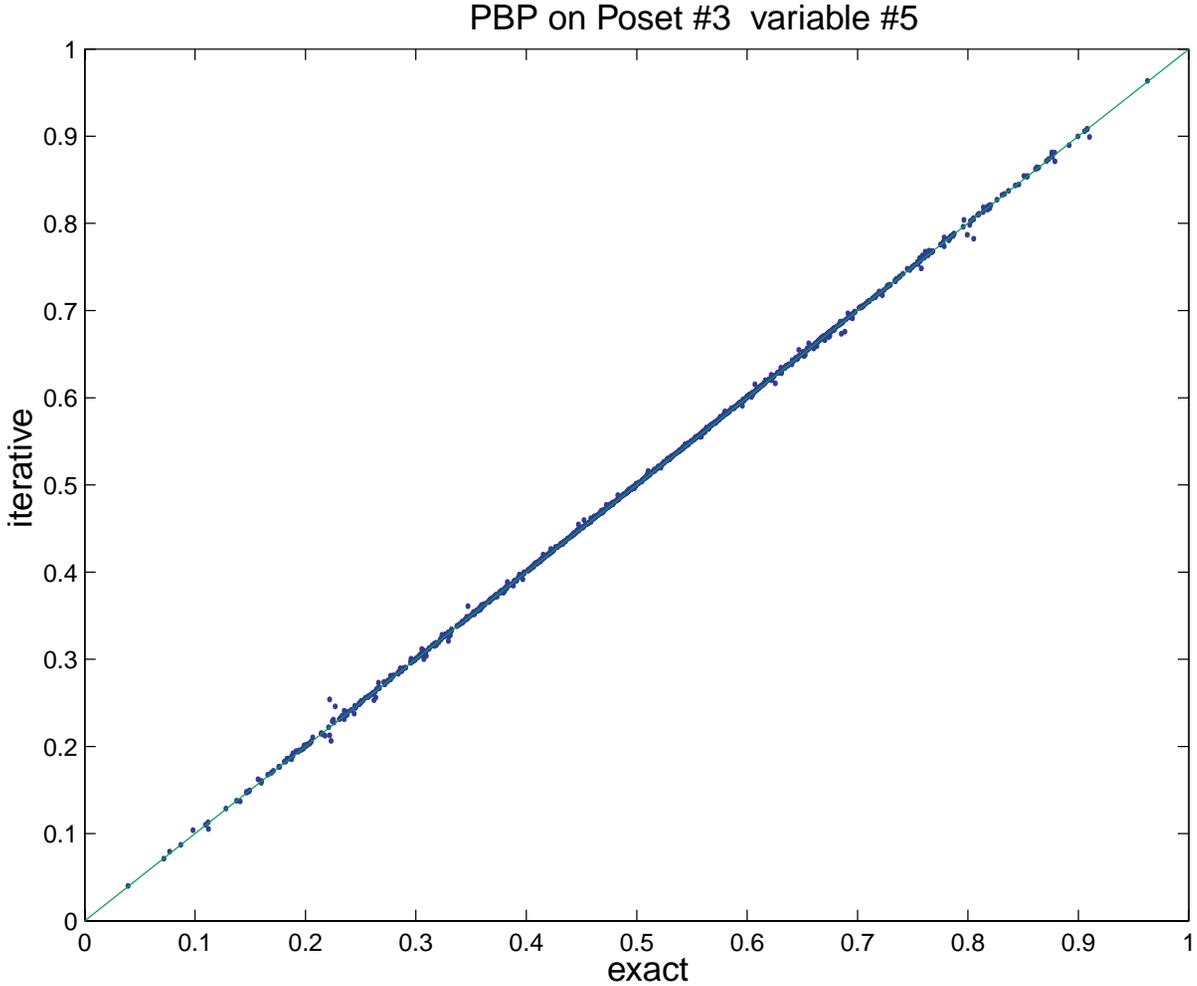
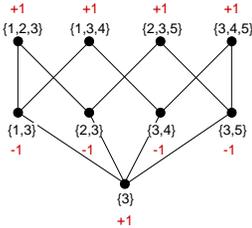
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Why Does It Work?

## Why Does It Work?

- No one really knows, but ...

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- The PBP algorithm can be viewed as an algorithm for minimizing a certain “energy” function. There is a one-to-one correspondence between the fixed points of PBP and the stationary points of this energy surface.

## More Precisely: The Bethe-Kikuchi Approximation

- We know

$$F = \min_{b(\mathbf{x})} \tilde{F}(b(\mathbf{x}))$$

$$B(\mathbf{x}) = \operatorname{argmin}_{b(\mathbf{x})} \tilde{F}(b(\mathbf{x})).$$

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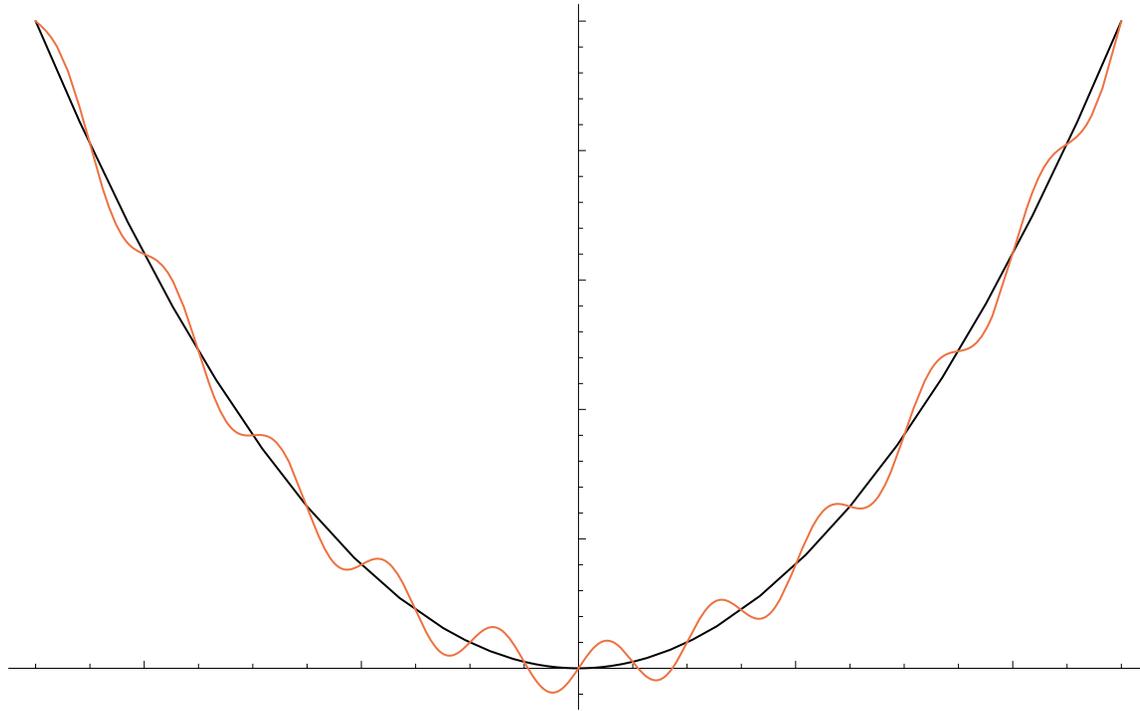
- We approximate  $\tilde{F}(b(\mathbf{x}))$  with something that depends only on the poset  $P$  and the marginals  $b_\rho(\mathbf{x}_\rho)$  of  $b(\mathbf{x})$ :

$$\tilde{F}_P(b(\mathbf{x})) = \sum_{\rho \in P} \phi(\rho) \tilde{F}_\rho(b_\rho(\mathbf{x}_\rho)),$$

where  $\tilde{F}_\rho(b_\rho(\mathbf{x}_\rho))$  is the local free energy at  $\rho$ , defined as

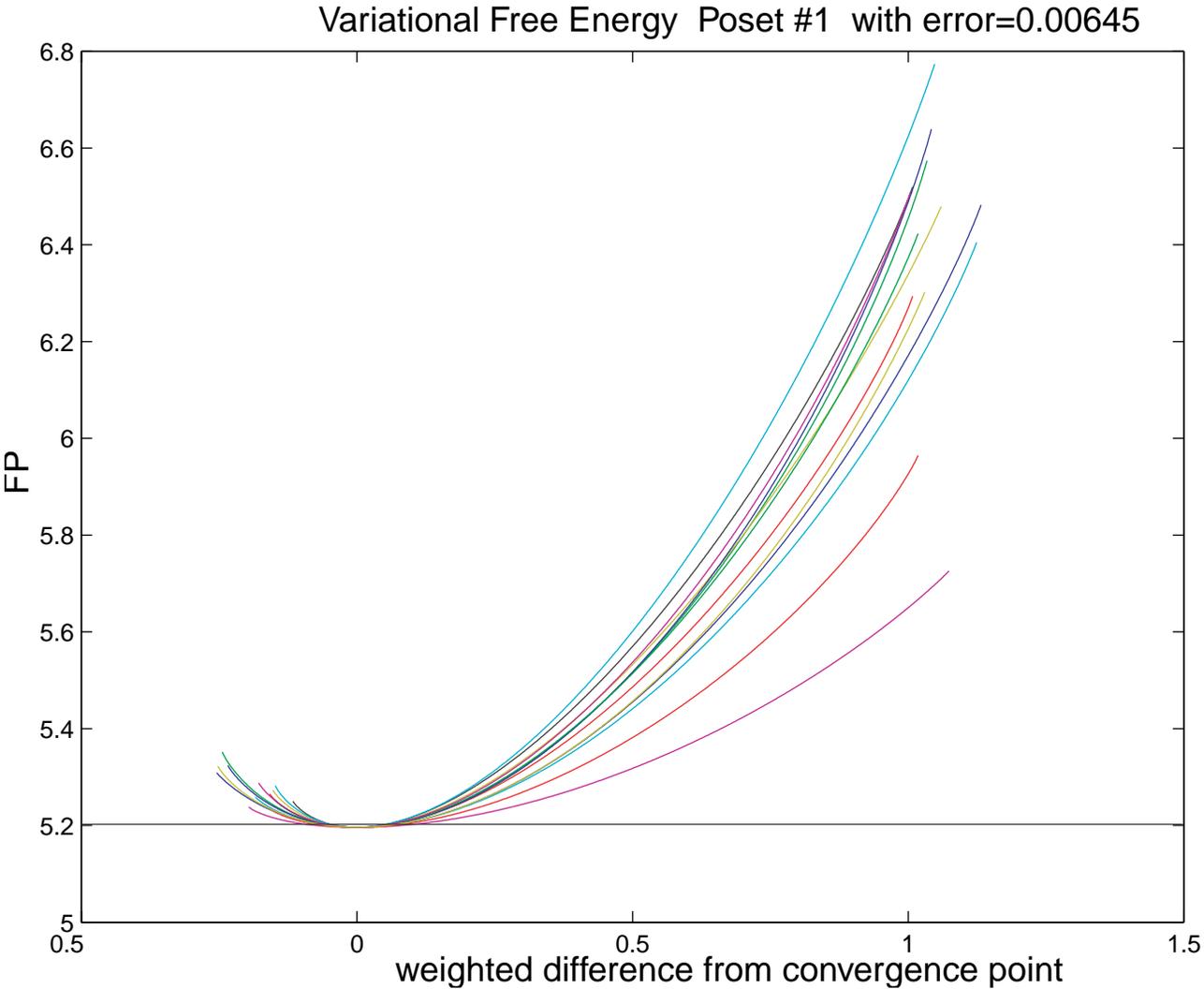
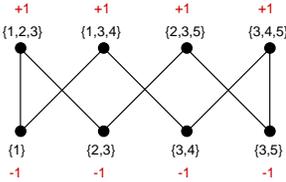
$$\sum_{\mathbf{x}_\rho} b_\rho(\mathbf{x}_\rho) E_\rho(\mathbf{x}_\rho) + \sum_{\mathbf{x}_\rho} b_\rho(\mathbf{x}_\rho) \ln b_\rho(\mathbf{x}_\rho).$$

## An Analogy:

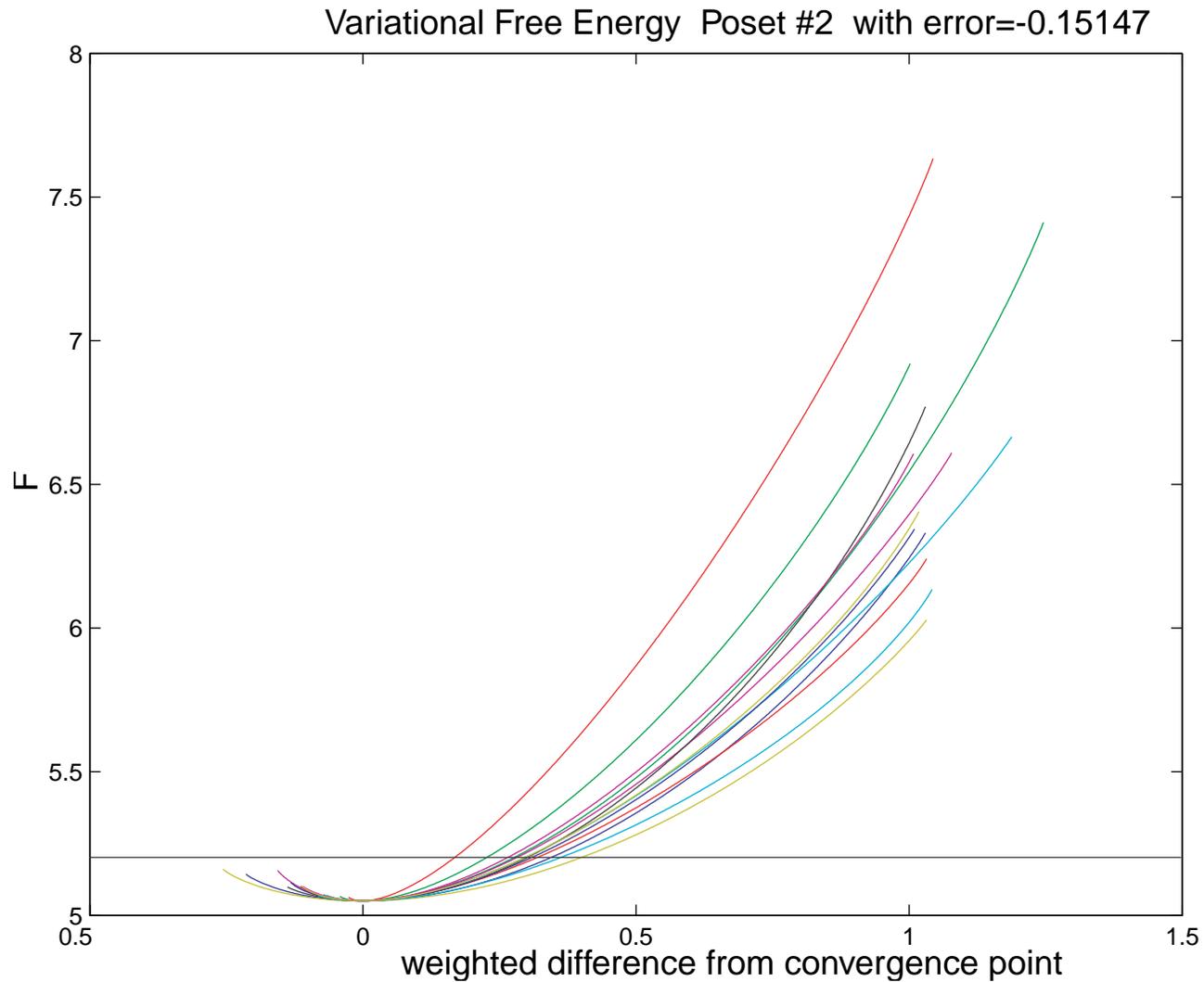
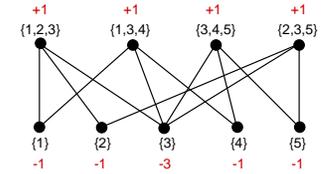


- Black line =  $\tilde{F}$
- Colored line =  $\tilde{F}_P$ .
- The hope is that  $\min_{\{b_\rho(\mathbf{x}_\rho)\}} \tilde{F}_P \approx \min_{b(\mathbf{x})} \tilde{F} = F$ .

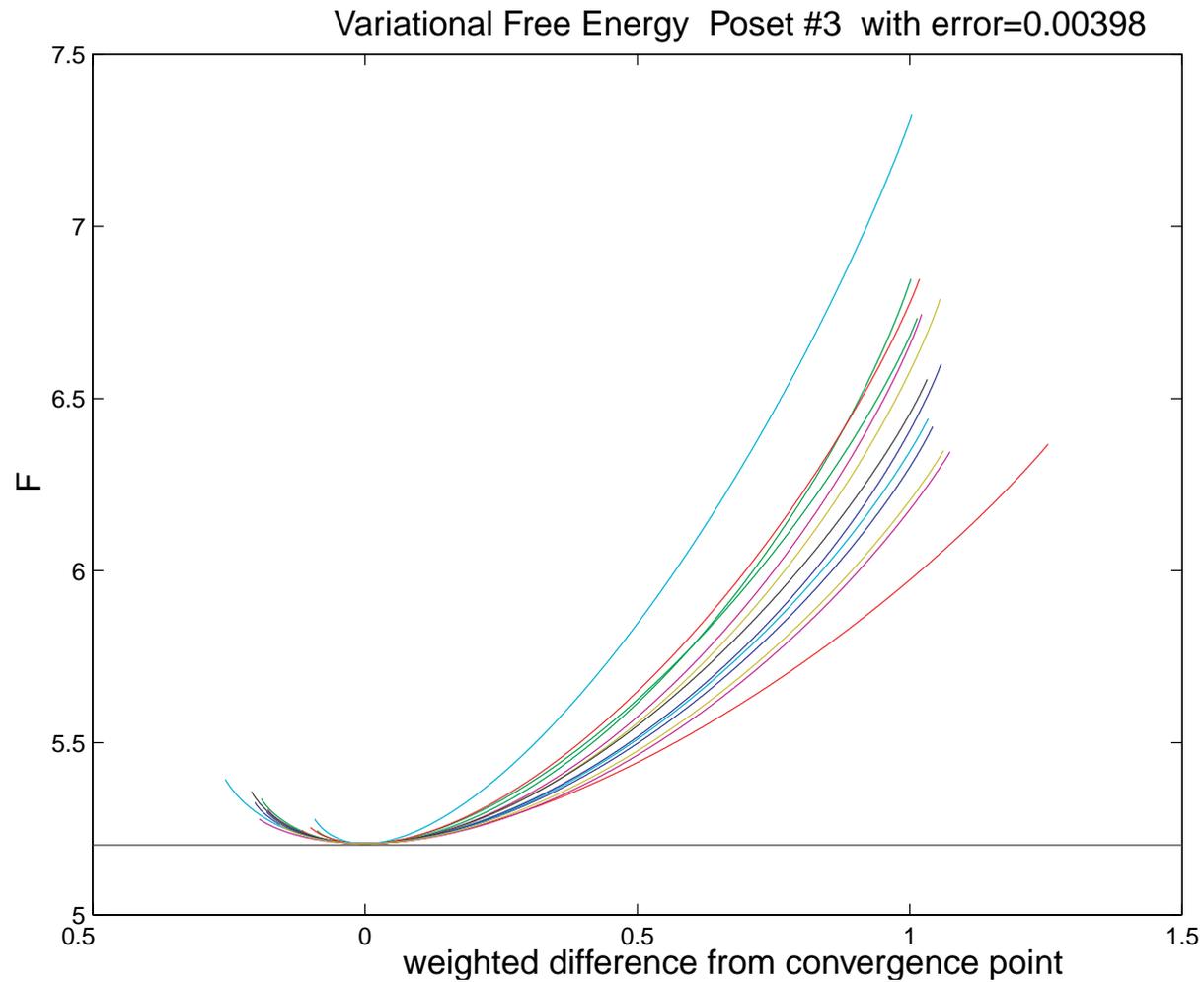
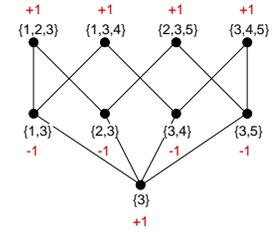
# Poset Number One — The BK Approximation



# Poset Number Two — The BK Approximation



# Poset Number Three — The BK Approximation



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- What is the relationship between the BK approximate free energy and the exact (Helmholtz), free energy?
- Can other combinatorial optimization methods, e.g. simulated annealing, be used to minimize  $\tilde{F}_P$ , thereby leading to alternative “BP” algorithms?